SECTION 3

ANALYSIS OF SEVERAL HIGH-PRESSURE CONTAINER DESIGN CONCEPTS

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SUMMARY FOR SECTION 3

Five types of pressure-vessel designs were analyzed in detail: a multiring container, a ring-segment container, a ring-fluid-segment container, a pin-segment container and a ring-fluid-ring container. (These are illustrated in Figures 39 and 40 of the text.) The multiring container is made up of cylindrical ring components. The ring-segment container is like the multiring container except that the second ring, adjacent to the liner, is a segmented ring. The ring-fluid-segment container is a combination of a ring-segment container on the inside with a multiring container on the outside, and with a fluid support pressure in between. In the ring-fluid-ring container, the inner ring is of single or multiring construction. The pin-segment container has a cylindrical inner liner supported by a pinned segment-plate arrangement. A wirewrapped (strip-wound) vessel and a controlled fluid-fill vessel were also considered but in less detail.

The four types of pressure vessel designs shown in Figure 39 were analyzed and reported in Interim Reports III, IV and V. (20, 21, 22) These analyses are described in detail in this section. Though the concept of the ring-fluid-ring design was reported in Interim Report IV, its complete analysis is reported for the first time in this section.

The operating cycle of high-pressure containers for hydrostatic extrusion and forming consists of application of the pressure needed, followed by a decrease in the pressure to zero. Such highly cyclic conditions coupled with extreme operating pressures can be expected to cause fatigue failures of the containers. A fatigue strength criterion was selected as the basis of the study because a high-pressure container for commercial application should, of course, be capable of repeated use without frequent failure.

To achieve the desired high pressure it was found necessary to use high-strength liner materials. For the high-strength steels (ultimate tensile strengths of 250,000 psi and greater) a maximum-tensile-stress criterion of fatigue was assumed and available uniaxial fatigue data from the literature were used in design evaluations. However, the fatigue behavior was left arbitrary in the analysis by formulating the analysis in terms of α_r and α_m , semirange and mean tensile stress parameters. The outer rings of the containers were assumed to be of more ductile materials in order to avoid catastrophic failures. A maximum shear criterion of fatigue was used for the ductile outer rings and the Goodman relation was used to relate the semirange and mean shear stresses.

For the analysis, equations were derived that relate the interface and the radial deformations between components. Elasticity solutions for stress and deformations were used together with fatigue relations to determine formulas for maximum bore pressures. Stresses due to the bore pressure and shrink-fit assembly were analyzed. The effect of temperature change (from operating temperature to room temperature) upon the prestresses (residual stresses) was included. The analyses for maximum pressure capability, residual stresses, and required shrink-fit interferences were programmed for calculation on Battelle's CDC 3400 and CDC 6400 computers.

Theoretically, large pressures (up to 1,000,000 psi in the ring-fluid-segment design) were found to be possible in the containers. However, designs based on the theoretical pressures were not always considered practicable because of manufacturing and assembly limitations. For example, a ring-fluid-segment container designed to a theoretical maximum pressure capability of 450,000 psi requires outside diameters of 88.0 inches and 218.0 inches for 6- and 15-inch-diameter bore designs, respectively. Such large-diameter cylinders would present problems in producibility, heat-treating, and transportation. This container design also requires a shrink-fit interference of 0.0128 in./in., which is difficult, if not impossible, to achieve in assembly. This large interference requirement is necessary to overcome excessive deformation of segments. Also, relatively larger outside diameters are required for segmented containers because segments offer no hoop support to the liner. These are distinct disadvantages of containers using segments.

Because of the practicable design limitations, the designs were evaluated for outside diameters limited to 72 inches and interferences limited to 0.007 in./in. maximum. High-strength liner materials of 300,000 psi ultimate tensile strength were assumed for which some fatigue data were available. A fatigue life of 10^4-10^5 cycles was selected for ideal conditions, i.e., no stress concentrations or material flaws in the liner. On this basis, the predictions of maximum pressure capability for 6-inch-diameter bore designs, for example, are as follows:

Container	Outside Diameter, inches	Maximum Pressure, p, psi
Multiring	51.0	300,000
Ring-segment	60.0	290,000
Ring-fluid-segment	72.0	286,000
Pin-segment	72.0	195,000

These pressure capabilities apply at room or elevated temperatures, provided the ultimate strength of the liner is 300,000 psi at temperature. Higher maximum pressures are theoretically possible with higher strength materials. For example, a maximum pressure of 450,000 psi would be predicted for a multiring container with a 450,000 psi ultimate strength liner material, if such a material could be found that had the same proportionate increase in its fatigue strength.

Residual stress limitations were also found for containers designed for hightemperature use. If the coefficient of thermal expansion of the liner is smaller than that of the outer components, then a decrease in temperature from operating temperature to room temperature may cause excessive residual stresses in the liner. Therefore, a higher coefficient of thermal expansion would be recommended for the liner.

There are other possible material limitations. The design evaluations conducted herein were based necessarily on the uniaxial fatigue data available for the liner materials, although a biaxial or triaxial state of stress exists in a pressure container. Also, a compressive mean stress on the liner was assumed beneficial. However, fatigue behavior of high-strength steels under combined stresses and compressive mean stress is unknown. In addition to fabrication and transportation difficulties, heat treatment of large cylindrical forgings may also present problems. In this respect a pin-segmentplate arrangement or a strip-wound layer offers advantages as a replacement of cylindrical rings for outer support members. A material's study is proposed to determine data on the important properties of high-strength materials for high-pressure-container applications.

Based on the design study of the four containers listed above, the ring-fluid-ring design was suggested. This design makes use of the benefits of fluid-support pressure and prestress from shrink fit. It avoids the difficulties associated with the segmented containers. It is shown in this analysis that a ring-fluid-ring container having a bore of 6-inch diameter could withstand a pressure level of 450,000 psi with an outer unit diameter of 60 inches. The fatigue life of this container would be 10^4-10^5 cycles.

Additional details of analysis are included in the appendices of this report. Bending deformations and stresses within segments, and derivations of shrink-fit interferences are some of the items included. Computer programs used for calculations are also briefly described.

SCOPE OF ANALYSIS

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The purpose of this study was to determine the maximum pressure capability of several designs of vessels for containing fluids at the pressures encountered in hydrostatic extrusion and other hydrostatic-forming processes. Containment of bore-fluid pressures up to 450,000 psi at room temperature and at temperatures of 500 F and 1000 F is considered.

The operating cycle of these high-pressure containers consists of application of the pressure needed for extrusion or forming, followed by a decrease in the pressure to zero. To be useful in production, the high-pressure containers must withstand a large number of such operating cycles. Therefore, fatigue strength of component materials must be an important design consideration. However, consideration of fatigue strength appears to be lacking in design analyses heretofore. The general method of design analysis has been to use a safety factor on the yield pressure. As the design pressures have been steadily increased, material limitations have necessitated lower factors of safety, sometimes less than 1:1. Consequently, fatigue failures are being experienced. Because of the extreme operating pressures being considered for hydrostatic extrusion and other forming operations (up to about 450,000 psi), it was essential that the various container-design concepts be analyzed and compared on the basis of a fatigue criterion.

In order to estimate the pressure capability of each container, stress analyses are conducted. Only stresses due to the bore pressure and shrink-fit assembly are analyzed; no thermal gradients are assumed present. However, the effect of temperature change (from operating temperature to room temperature) upon the prestress (residual stresses) is included in the analyses. Excessive residual stresses may result because of differences in thermal expansion of the component parts of each container.

Four types of pressure vessel designs were analyzed in detail. These are:

- (1) Multiring container
- (2) Ring-segment container
- (3) Ring-fluid-segment container
- (4) Pin-segment container.

The four concepts for cylindrical containers are shown in Figure 39. A wire-wrapped (strip-wound) vessel and a controlled fluid-fill, cylindrical-layered container also were considered, but only briefly.

As a result of these analyses, a further refinement of the ring-fluid-segment container was conceived in which the segments were replaced by a shrink-ring assembly as shown in Figure 40. An extended analysis of this advanced container design has been completed recently and is described for the first time in this report. A rigorous analysis of the advanced concept together with a more general formulation of fatigue criteria for multiring containers are reported separately at the end of this section.



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FIGURE 39. SCHEMATIC OF HIGH-PRESSURE-CONTAINER DESIGN CONCEPTS ANALYZED IN THE PRESENT STUDY



FIGURE 40. RING-FLUID-RING CONTAINER FOR HIGH PRESSURE

The design involves the combined use of interferencefit multi-ring construction with fluid-pressure support. The multiring container was one of the first design modifications of the monoblock, thick-walled cylinder*. An initial compressive stress at the bore is achieved by shrink-fit assembly of successive cylinders each manufactured to provide an interference fit with its mating cylinder. The multiring container has been analyzed on the basis of static shear strength by Manning^(23, 24, 25).

The ring-segment container with one outer ring was patented by Poulter in 1951. (26) One intent of this design is to reduce the pressure acting upon the outer ring by using a segmented cylinder to redistribute the pressure at a larger diameter. However, the inner cylinder is always subject to the bore pressure. The external diameter of the vessel necessarily increases with increasing segment size.

The ring-fluid-segment container makes use of the fluid-pressure support principle. This container is essentially constructed of two parts. The inner part is a ringsegment-type container with one outer ring, but with a fluid support pressure, p_3 , as shown in Figure 41. The outer part is a multiring container subject to an internal pressure, p_3 , the support pressure for the inner part. The advantage of this design is that the fluid pressure (p_3) provides a compressive hoop stress at the bore which counteracts the tensile hoop stress resulting from the bore pressure, p. Theoretically, p_3 can be changed in proportion to the change in bore pressure in order to reduce the bore stress over an entire cycle of bore pressure. This variation of p_3 with the bore pressure is assumed in the analysis.

The origin of the ring-fluid-segment concept is not clear. Ballhausen patented an approach of this sort in 1963. (27) Another application of the same principle was patented by G. Gerard and J. Brayman, also in 1963. (28) A similar design, but with additional features, was reported by F. J. Fuchs in 1965. (29)

The pin-segment design is an approach proposed by Zeitlin, Brayman, and Boggio.⁽³⁰⁾ Like the ring-segment container this vessel also uses segments to reduce the pressure that must be carried by the external support. Unlike the ring-segment container, the pin-segment container has segmented disks (thin plates) rather than segmented cylinders. Also, the external supporting members in this case are pins rather than an external ring. The pins carry the reaction to the bore pressure predominantly in shear.

The ring-fluid-ring container shown in Figure 40, like the ring-fluid-segment design, makes use of the fluid pressure support principle. The use of an inner multiring unit, however, avoids the numerous difficulties encountered in segmental design. Since suggestion of the design, description of similar designs have been noted in the literature. (31, 32, 33) Thus, the design is not new, but the analytical-design basis described toward the end of this section is. It is believed that this program is the first to incorporate the fatigue-strength design of high-pressure containers on a rigorous basis.

All five containers have one thing in common: the liner is subject to the full bore pressure. The five containers differ in the manner and in the amount they constrain the liner.

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^{*}The monoblock, thick-wall cylinder is the simplest type of pressure container. However, for the very high pressure levels considered in this study it is a relatively inefficient design.



FIGURE 41. NOTATIONS USED FOR ANALYSIS OF CONTAINER-DESIGN CONCEPTS

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BASIS AND METHOD OF ANALYSIS

In this study the four design concepts for high-pressure containers are evaluated on the basis of a selected strength criterion for the component materials. Different strength criteria could be chosen, each of which could lead to different predictions of maximum pressure capability. If rupture under static load is the strength criterion then a burst pressure can be predicted. This pressure would be higher than the yield pressure predicted on the basis of static yield strength. However, a vessel subject to a great number of pressure cycles at less than the yield pressure could fail by fatigue. A high-pressure container for commercial hydrostatic extrusion should, of course, be capable of repeated use without frequent failure. Therefore, it was considered essential that a fatigue strength criterion be used as the basis of evaluation in this study.

It also has to be ascertained what kind of stress and strain analysis is needed – elastic, plastic, or elastic-plastic. This is determined from the fatigue life desired. Manson and Hirschberg have shown that for most materials, failure by low-cycle fatigue (life less than about 1000 cycles) involves almost entirely plastic strain. (34) Above about 1000 cycles life the amount of plastic strain is appreciably smaller, and above 100,000 cycles life the plastic strain is negligible. For the relatively high-strength materials, however, the strain at fracture is predominantly elastic for lifetimes as low as 100 cycles. Because lifetimes greater than 1000 cycles are desirable in commercial applications, and since high pressures require use of high-strength materials, elasticity theory rather than plastic or elastic-plastic analysis is used. Use of elastic theory rather than elastic-plastic theory also aids the study because elasticity solutions are easier to formulate and can be superimposed.

For the analysis, equations are derived that relate the interface pressures and the radial deformations between components. Elasticity solutions for stresses and deformations are used together with fatigue relations to determine formulas for maximum bore pressures.

METHOD OF PARAMETER NOTATION

The components of each design are identified from the inside out by the numbers 1, 2, 3, ..., N. N refers to the outermost component. Figure 41 shows the use of radii r_{n-1} and r_n to denote the inner and outer radii of component number n.

For the multiring container all the components are circular hollow cylinders. For the ring-segment and ring-fluid-segment containers, Component 2 refers to the segments. The only exception to the notation on the radii occurs in the pin-segment design where the segment is divided for analysis into two parts and where r_2 is the radius to the inside of the pins as shown in Figure 41.

The operating pressures and the residual pressures are identified by q_n and p_n^* respectively. Because the outer radius of each container refers to a free surface, the pressure there is zero,

$$p_N = 0$$
, $q_N = 0$ (4a, b)

The definition of the q_n gives

The wall ratio for component n is denoted by k_n . The overall diameter ratio of the container is denoted as K, where

 $k_n = \frac{r_n}{r_n - 1}$

 $K = \frac{r_N}{r}$

90

and

*See list of symbols for definitions.

(5)

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FATIGUE CRITERIA

Two fatigue criteria are formulated here in order that both relatively low-strength ductile materials and high-strength, more brittle materials may be used in one design. The intention is to use high-strength steels as liner materials and lower strength ductile steels for the outer cylinders in order to prevent catastrophic brittle failure.

Fatigue Criterion for Ductile Outer Cylinders

From both torsion and triaxial fatigue tests on low-strength steels (120 to 150 ksi ultimate strength) conducted by Morrison, Crossland, and $Parry^{(35)}$ it is concluded that a shear criterion applies. Therefore, a shear theory of failure is assumed for outer rings made of ductile steel.

To formulate a fatigue relation, the semirange in shear stress and the mean shear stress are needed. These stresses are defined as

$$S_{r} = \frac{S_{max} - S_{min}}{2}$$

$$S_{m} = \frac{S_{max} + S_{min}}{2}$$
(6a, b)

respectively.

A linear fatigue relation in terms of shear stresses is assumed. This relation is

$$\frac{S_r}{S_e} + \frac{S_m}{S_u} = 1, \text{ for } S_m \ge 0$$

where S_e is the endurance limit in shear and S_u is the ultimate shear stress. For $S_u = 1/2 \sigma_u$, where σ_u is the ultimate tensile stress, this relation can be rewritten as:

$$\frac{S_r}{S_e} + \frac{2S_m}{\sigma_u} = 1, \ S_m \stackrel{\geq}{=} 0$$
(7)

The stresses S_r and S_m given by Equations (6a, b) can be calculated from elasticity solutions. In order to employ the fatigue relation (7) for general use, it is assumed that S_e can be related to S_u . This is a valid assumption as shown by Morrison, et al⁽³⁵⁾. Referring to Reference (35), the ratio S_e/S_u can be established. Table XLI lists some fatigue data and results of calculation of S_e from Equation (7).

From Table XLI is is evident that fluid pressure contacting the material surface has a detrimental effect on fatigue strength; the endurance limit S_e for unprotected triaxial fatigue specimens is lower than that for torsional specimens. However, protection of the bore of triaxial specimens increases S_e under triaxial fatigue to a value equal that for torsional fatigue. Since in the high-pressure containers, outer cylinders are subject to interface contact pressures and not to fluid pressures, it is assumed that the data for a protected bore in Table XLI are applicable in the present analysis. Therefore, the following relation between S_e and σ_u is assumed:

S

$$e = \frac{1}{3} \sigma_u \tag{8}$$

Substitution of Relation (8) into (7) gives

$$3S_r + 2S_m = \sigma$$
, where $\sigma \leq \sigma_u$ (9)

Equation (9) now has a factor of safety, σ_u/σ , and can be expected to predict lifetimes of 10⁶ cycles and greater for ductile steels based upon the linear fatigue relation and available fatigue data. (Of course, stress concentration factors due to geometrical discontinuities or material flaws would reduce the expected lifetime.)

	Stresses, psi				
Test	ďu	s _r	Sm	s _e	s _e /σ _u
Torsion	126,000	43,700	0	43,700	0.347
	149,000	52,900	0	52,900	0.354
Triaxial (unpro-	126,000	20,900	20,900	31, 300(c)	0.248
tected bore)	149,000	26, 300	26,300	40,600	0.273
Triaxial ^(b) (pro- tected bore)	126,000	26,500	26,500	45,900	0.363

TABLE XLI. TORSIONAL AND TRIAXIAL FATIGUE DATA ON VIBRAC STEEL^(a)

(a) From Reference (35). Composition of this steel in weight percent is 0.29 to 0.3 C, 0.14 to 0.17 Si, 0.64 to 0.69 Mn, 0.015 S, 0.013 P, 2.53 to 2.58 Ni, 0.57 to 0.60 Cr, 0.57 to 0.60 Mo.

(b) The bore of the cylindrical specimens was protected with a neoprene covering.

(c) S_{ρ} for the triaxial tests is calculated from Equation (7).

Fatigue Criterion for High-Strength Liner

Triaxial fatigue data on high-strength steels ($\sigma_u \ge 250$ ksi) are not available. Fatigue data in general are very limited. Therefore, a fatigue criterion for highstrength steels under triaxial fatigue cannot be as well established as it was for the lower strength steels. The high-strength steels are expected to fail in a brittle manner. Accordingly, a maximum tensile stress criterion of fatigue failure is postulated.

Because fatigue data are limited while tensile data are available the tensile stresses $(\sigma)_r$ and $(\sigma)_m$ are related to the ultimate tensile strength by introduction of two parameters α_r and α_m . These are defined as follows:

$$\alpha_{\mathbf{r}} = \frac{(\sigma)_{\mathbf{r}}}{\sigma_{1}}, \qquad \alpha_{\mathbf{m}} = \frac{(\sigma)_{\mathbf{m}}}{\sigma_{1}}$$
 (10a, b)

where $(\sigma)_r$ is the semirange in stress, $(\sigma)_m$ is the mean stress^{*}, and σ_1 is less than or equal to the ultimate tensile strength depending upon the factor of safety desired. In order to get some estimations of what values α_r and α_m may be, some data from the literature are tabulated in Tables XLII, XLIII, and XLIV. These data are for rotatingbeam and push-pull tests.

The fatigue life again is found to depend on the range in stress and the mean stress, and upon the temperature. This dependence is illustrated in Figure 42 for 10⁴ to 10⁵ cycles life in terms of the parameters α_r and α_m . (Points (α_r , α_m) above the curves in Figure 42 would correspond to $<10^4-10^5$ cycles life and points below the curves would correspond to $>10^4-10^5$ cycles life.) The 1000 F temperature data are for Vascojet 1000. Although α_r increases with temperature for this steel, the ultimate tensile strength decreases and the fatigue strength at 10^4 to 10^5 cycles for $\alpha_m = 0$ remains nearly constant over the temperature range of 75 F to 1000 F.



FIGURE 42. FATIGUE DIAGRAM FOR 10⁴-10⁵ CYCLES LIFE FOR HIGH-STRENGTH STEELS AT TEMPERATURES OF 75 F TO 1000 F

 α_r and α_m are defined by Equations (10a, b)

^{*(} σ)_r and (σ)_m are defined by expressions similar to Equations (6a, b) for S_r and S_m.

entrant roat - patrion to to to to	ina, ini, ini There dat	Ultimate Tensile Strength,	Yield Tensile Strength.	α _r , Stress Range Parameter ^(a)			
Material	Reference	ksi	ksi	104	105	106	107
18% Ni maraging	(36)	300	280		0.49	0.43	0.41
	(38)	295 270	285 265	0.68 0.74	0.44 0.43	0.38	0.36 0.37
H-11 (CEVM)	(38)	250-280	210-230	0.75	0.57	0.54	0.54
D6AC	(39)(c)	270	237	0.66	0.41	0.37	0.37
Vascojet 1000	(39)(c)	309	251		0.45	0.29	0.29

TABLE XLII. FATIGUE STRENGTHS OF HIGH-STRENGTH STEELS FROM ROOM-TEMPERATURE ROTATING-BEAM TESTS, $\alpha_m = 0$

(a) $a_r \equiv (\sigma)_r / \sigma_u$, $a_m \equiv (\sigma)_m / \sigma_u$, where $(\sigma)_r$, $(\sigma)_m$, σ_u are the semirange, mean, and ultimate tensile stresses, respectively. (b) These are stated to be 90 percent probability data. (c) Tests in Reference (39) were push-pull tests with, $a_m = 0$.

TABLE XLIII.	FATIGUE STRENGTHS OF HIGH-STRENGTH STEELS FROM	
	ROOM- TEMPERATURE PUSH-PULL TESTS, $\alpha_m = \alpha_r$	

brod	lor an Alox 2 is	Ultimate Tensile Strength.	Yield Tensile Strength.	α _r , Str	ess Ran for Cy	lge Para cles	.meter(a),
Material	Reference	ksi	ksi	104	105	106	107
18% Ni maraging steel	(38)	295 270	285 265	0.40 0.43	0.25 0.28	0.22 0.25	0.22 0.24
H-11 (CEVM)	(38)	280-300		0.38	0.31	0.29	0.29
D6AC	(39)	270	237	0.44	0.33	0.28	0.28
Vascojet 1000	(39)	309	251		0.33	0.27	0.19

(a) $a_r \equiv (\sigma)_r / \sigma_u, \sigma_m \equiv (\sigma)_m / \sigma_u$, where $(\sigma)_r$, $(\sigma)_m, \sigma_u$ are the semirange, mean, and ultimate tensile stresses, respectively.

	Test Temp.,	Ultimate Tensile Strength,	Yield Tensile Strength,	Test	α_r , Stres	ss Range for Cyc	Paramet les	er(b),
Material	F	ksi	ksi	Conditions(c)	104	105	106	107
	450	260	175	$\begin{cases} \alpha_{m} = 0 \\ \alpha_{m} = \alpha_{r} \end{cases}$	0.56(d) 0.41	0.48 0.35	0.40 0.31	0.31 0.26
D6AC	550	230	160	$\begin{cases} \alpha_{m} = 0 \\ \alpha_{m} = \alpha_{r} \end{cases}$	0.65 0.44	0.52 0.38	0.41 0.34	0.33 0.29
We appoint 1000	800	260	200	$\begin{cases} \alpha_{m} = 0 \\ \dot{\alpha}_{m} = \alpha_{r} \end{cases}$	0.69	0.56 0.40	0.42 0.32	0.31 0.23
vascojet 1000	L 1000	230	176	$\begin{cases} \alpha_{m} = 0 \\ \alpha_{m} = \alpha_{r} \end{cases}$	0.75(d)	0.61 0.39	0.43 0.27	0.26

TABLE XLIV. FATIGUE STRENGTHS OF HIGH-STRENGTH STEELS FROM PUSH-PULL TESTS AT ELEVATED TEMPERATURES(a)

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(a) Data are taken from Reference (39).

(b) $a_r \equiv (\sigma)_r / \sigma_u, \sigma_m \equiv (\sigma)_m / \sigma_u$, where $(\sigma)_r$, $(\sigma)_m$, σ_u are the semirange, mean, and ultimate tensile stresses, respectively, at temperature. (c) The cycle rate was 3100 cps. (d) S-N curve extrapolated to 10⁴ cycles.

The fatigue data available are only for positive and zero mean stresses. However, there is evidence that compressive mean stress may significantly increase the fatigue strength (35, 40). The reasons for this are thought to be that compression may reduce the detrimental effect of fluid pressure entering minute cracks or voids in the material and the compression may restrain such flaws from growing. Since the liner of a high-pressure container can be precompressed by shrink-fit assembly, an important factor in triaxial fatigue may be the prestress that can be initially provided. Therefore, for 10^4 to 10^5 cycles triaxial fatigue life, α_r and α_m are assumed to be

$$\alpha_r = 0.5, \ \alpha_m = -0.5$$
 (11a, b)

as indicated in Figure 42. With $\alpha_m = -\alpha_r$ the maximum tensile stress at the bore would be zero.

In order to approximate a life of one cycle, it is assumed that

$$\alpha_r = 1.0, \ \alpha_m = 0, \text{ for one cycle}$$
 (12a, b)

which represents a cycle between $\pm \sigma_u$, the ultimate strength.

XXVIII

ELASTICITY SOLUTIONS

Cylindrical polar coordinates (r, θ , z) are used in the analysis. Axial symmetry is assumed; the stresses are independent of the angle θ . End effects are not considered*; the stresses found are independent of the axial coordinate z.

Elasticity Solutions for a Cylinder

The two-dimensional solutions for a cylinder loaded by uniform inner and outer pressures is given by Timoshenko and Goodier(41). The expressions for stresses and displacement in cylinder n are

$$\sigma_{r} = \frac{1}{k_{n}^{2} - 1} \left[p_{n-1} - p_{n}k_{n}^{2} - (p_{n-1} - p_{n}) \left(\frac{r_{n}}{r}\right)^{2} \right]$$

$$\sigma_{\theta} = \frac{1}{k_{n}^{2} - 1} \left[p_{n-1} - p_{n}k_{n}^{2} + (p_{n-1} - p_{n}) \left(\frac{r_{n}}{r}\right)^{2} \right]$$
(13a-c)

$$\frac{u}{r} = \frac{1}{E_{n}(k_{n}^{2}-1)} \left[(1 - \nu) (p_{n-1} - p_{n}k_{n}^{2}) + (1 + \nu) (p_{n-1} - p_{n}) (\frac{r_{n}}{r})^{2} \right]$$

$$v = 0$$
(14a, b)

where σ_r , σ_{θ} , and $\tau_{r\theta}$ are the radial stress, hoop stress, and shear stress, respectively, and where u and v are the radial and circumferential displacements, respectively. (The radii r_n , the pressures p_n , and the wall ratios k_n have been defined previously.) Equation (13a-c) also gives the residual stresses if the operating pressures p_n are replaced by the residual pressures q_n .

For a fatigue analysis of a cylinder of ductile material the range and mean shear stresses are needed. The greatest range in the shear stress in a cylinder occurs at the bore on a plane oriented at 45 degrees to the r and θ axes. The shear stress there is given by

$$S = \frac{\sigma \theta - \sigma_r}{2}$$
(15)

^{*}It may be important to consider end effects depending upon the method of end closure in the design. These effects and possible axial stresses resulting from large shrink fits may not be negligible.

Formulating the range in stress from the Definition (6a), we get

$$S_{r} = \frac{1}{2} \left[\frac{\sigma_{\theta}(p_{n}, p_{n-1}) - \sigma_{r}(p_{n}, p_{n-1})}{2} - \frac{\sigma_{\theta}(q_{n}, q_{n-1}) - \sigma_{r}(q_{n}, q_{n-1})}{2} \right] \text{ at } r = r_{n-1} ,$$

hence,

$$S_{r} = \frac{k_{n}^{2}}{2(k_{n}^{2}-1)} \left[(p_{n-1} - p_{n}) - (q_{n-1} - q_{n}) \right], \text{ at } r = r_{n-1}$$
(16)

The mean shear stress at the same location on the same plane is

$$S_{m} = \frac{k_{n}^{2}}{2(k_{n}^{2}-1)} [(p_{n-1} - p_{n}) + (q_{n-1} - q_{n})], \text{ at } r = r_{n-1}$$
(17)

Elasticity Solutions for Segmented Components

Elasticity solutions for the segments were derived. The derivations are outlined in Appendix I and only the results are given here. There are two types of segments. The ring segment is loaded by p_1 at r_1 and by p_2 at r_2 . The pin segment is loaded by p_1 at r_1 but by more complex loading at r_2 .

Ring Segment

The results for the ring segment are:

$$\sigma_{r} = (\sigma_{r})_{c} + \frac{4M_{1}p_{1}}{\beta_{1}} f_{1}(r)$$

$$\sigma_{\theta} = (\sigma_{\theta})_{c} + \frac{4M_{1}p_{1}}{\beta_{1}} f_{2}(r)$$

 $\tau_{r\theta} = 0$

$$\frac{u}{r} = (u)_{c} + \frac{M_{1}p_{1}}{E_{2}\beta_{1}} f_{3}(r) + \frac{G_{1}p_{1}}{r} \cos \theta$$

$$\frac{v}{r} = \frac{8M_{1}p_{1}}{E_{2}\beta_{1}} (k_{2}^{2} - 1) \theta - \frac{G_{1}p_{1}}{r} \sin \theta \qquad (19a, b)$$

(18a-c)

where:

$$f_{1}(\mathbf{r}) = \left(\frac{\mathbf{r}_{2}}{\mathbf{r}}\right)^{2} \log k_{2} + k_{2}^{2} \log \left(\frac{\mathbf{r}}{\mathbf{r}_{2}}\right) + \log \left(\frac{\mathbf{r}_{1}}{\mathbf{r}}\right)$$

$$f_{2}(\mathbf{r}) = -\left(\frac{\mathbf{r}_{2}}{\mathbf{r}}\right) \log k_{2} + k_{2}^{2} \log \left(\frac{\mathbf{r}}{\mathbf{r}_{2}}\right) + \log \left(\frac{\mathbf{r}_{1}}{\mathbf{r}}\right) + k_{2}^{2} - 1$$

$$f_{3}(\mathbf{r}) = -4 \left(1 + \nu\right) \left(\frac{\mathbf{r}_{2}}{\mathbf{r}}\right) \log k_{2} + 4(1 - \nu) \left[k_{2}^{2} \log \left(\frac{\mathbf{r}}{\mathbf{r}_{2}}\right) \right]$$

$$(20a-c)$$

$$-\log \left(\frac{\mathbf{r}}{\mathbf{r}_{1}}\right) - 4 \left(k_{2}^{2} - 1\right)$$

and where $(\sigma_r)_c$, $(\sigma_\theta)_c$, and $(u)_c$ are given by Equations (13a-c) and (14a, b) for $k_n = k_2$, $p_{n-1} = p_1$, $p_n = p_2$, and $E_n = E_2$. For a ring segment p_1 and p_2 are related for equilibrium as follows:

$$p_2 = p_1/k_2$$
 (21)

Formulas for the constants β_1 , G_1 , and M_1 (functions of k_2) are given in Appendix I. M_1 represents a bending moment that causes a bending displacement v as shown in Equation (19b).

Pin Segment

The solution for the pin segment is more complicated due to the pin loading at r_2 . The resulting expressions are:

$$\sigma_{r} = (\sigma_{r})_{c} + \frac{4M_{2}p_{1}}{\beta_{1}} f_{1}(r) + g_{m1}(r) \cos m\theta$$

$$\sigma_{\theta} = (\sigma_{\theta})_{c} + \frac{4M_{2}p_{1}}{\beta_{1}} f_{2}(r) + g_{m2}(r) \cos m\theta \qquad (22a-c)$$

$$\tau_{r\theta} = g_{m3}(r) \sin m\theta$$

$$\frac{u}{r} = (u)_{c} + \frac{M_{2}p_{1}}{E_{2}\beta_{1}} f_{3}(r) + \frac{G_{2}p_{1}}{r} \cos \theta + \frac{1}{E_{2}} g_{m4}(r) \cos m\theta$$
(23a,b)
$$\frac{v}{r} = \frac{8M_{2}p_{1}}{E_{2}\beta_{1}} (k_{2}^{2} - 1) \theta - \frac{G_{2}p_{1}}{r} \sin \theta + \frac{1}{E_{2}} g_{m5}(r) \sin m\theta$$

where $(\sigma_r)_c$, $(\sigma_\theta)_c$, and $(u)_c$ are again given by Equations (13a-c) and (14a, b) for $k_n = k_2$, $p_{n-1} = p_1$, $p_n = p_2$, and $E_n = E_2$. For a pin segment p_2 is related to p_1 as follows:

$$p_2 = \frac{(m^2 - 1)(1 + 2\cos \pi/m)}{2(m^2 - 2)(1 + \cos \pi/m)} \quad (\frac{p_1}{k_2})$$
(24)

where m defined as

$$m = 2N_s$$
(25)

and where N_s is the number of segments per disc.

The functions $f_1(r)$, $f_2(r)$, and $f_3(r)$ are again given by Equations (20a-c) and β_1 , G_2 , M_2 , g_{m1} , ..., $g_{m5}(r)$ are given in Appendix I.

The elasticity solutions now can be used to determine formulas for maximum pressure capability from the fatigue relations. This is done in the next section.

NONDIMENSIONAL PARAMETER ANALYSIS

The maximum pressure a container will withstand is a function of the material fatigue strength, the amount of prestress, the number of components N, and the wall ratios k_n . To determine the function dependence on these variables and to determine the best designs, a nondimensional analysis is now presented. The calculations for the analysis of each design were programmed on Battelle's CDC 3400 computer.

Multiring Container

Static Shear Strength Analysis

Although a fatigue criterion of failure has been chosen it is illustrative to review an analysis based upon <u>static shear strength</u> for ductile materials first conducted by Manning⁽²³⁾. The method outlined here differs from that of Manning and is more straightforward. In this analysis the optimum design is found such that <u>each</u> component of the <u>same</u> material has the <u>same</u> value of maximum shear stress S under the pressure load p. The given information is $p_0 = p$, $p_N = 0$, and K. The unknowns are the interface pressures p_n , (N-1) in number; the k_n , N in number and S. The total unknowns are 2N. There are N equations resulting from Equation (15) and having the form

$$S = (p_{n-1} - p_n) \frac{k_n^2}{k_n^{2-1}}, n = 1, 2, ..., N$$
 (26)

There is the equation, $K = k_1 k_2 \dots k_n$, that relates the k_n and K. Also N-1 equations can be formulated from the requirement that S be a minimum, i.e.,

$$\frac{\partial S}{\partial k_n} = 0, n = 1, 2, \dots, N-1$$
 (27)

(There are not N equations in the Form (27) because there is one equation relating the k_n .) Thus, there are also 2N equations which can be solved for the 2N unknowns. The solution gives

$$p_n = p_{n-1} - \frac{(k_n^2 - 1)}{k_n^2} S, \quad n = 1, 2, ..., N-1$$
 (28)

$$k_1 = k_2 = \dots = k_N$$
 (29)

$$S = \frac{p}{N} \frac{K^{2/N}}{(K^{2/N} - 1)}$$
(30)

The residual pressures q_n and the required interferences for the shrink-fit assembly have yet to be found. The radial stress σ_{rn} at the radius r_n resulting from the bore pressure p is given by Equation (13a) with K replacing k_n , p replacing p_{n-1} , r_N replacing r_n , r_n replacing r, and $p_n = p_N = 0$. σ_{rn} becomes:

$$\sigma_{rn} = \frac{p}{K^2 - 1} (1 - k_{n+1}^2 k_{n+2}^2 \dots k_N^2)$$

The pressure p_n is the sum of q_n and $(-\sigma_{rn})$. Therefore,

$$q_n = p_n - (-\sigma_{rn}) \tag{32}$$

(31)

(33)

The interference as manufactured, Δ_n at r_n , is given by

$$\frac{\Delta_n}{r_n} = \frac{-u_n(r_n)}{r_n} + \frac{u_{n+1}(r_n)}{r_n}$$

where

 $u_n(r_n) = radial deformation at <math>r_n$ of cylinder N due to the residual pressure q_n at r_n and the residual pressure q_{n-1} at r_{n-1} .

and

 $u_{n+1}(r_n) = radial deformation at r_n of cylinder n+1 due to the residual pressure <math>q_n$ at r_n and the residual pressure q_{n+1} at r_{n+1} .

Substituting the Expressions (32) for q_n into Expressions (14a) for the u_n and substituting the results into Equation (33), we find that Δ_n/r_n reduces to:

$$\frac{\Delta_n}{r_n} = \frac{2p}{NE}$$
(34)

The result p/2S given by Equation (30) is plotted in Figure 43 for various N. The limit curve is given by

$$\left(\frac{p}{2S}\right)_{1\text{imit}} = \frac{K^2 - 1}{K^2}$$
 (35)

at which limit the minimum shear stress becomes equal to -S at the bore in the inner cylinder.

Figure 43 has been obtained under the assumption that $\frac{\sigma_{\theta} - \sigma_{r}}{2}$ always gives the maximum shear stress. As pointed out by Berman, the maximum shear stress in a closed-end container* is given by $\frac{\sigma_{z} - \sigma_{r}}{2}$ when $\sigma_{z} > \sigma_{\theta}$. (42) Therefore, it is important to know the limit to $\frac{p}{25}$ for which σ_{z} becomes equal to σ_{θ} . σ_{z} is given by

^{*}Containers for hydrostatic extrusion generally are not closed-end containers. The effect of axial stress is included here for completeness.

$$\sigma_z = \frac{p}{K^2 - 1}$$

 σ_{θ} is given by Equation (13b). Equating σ_{θ} at r_0 to σ_z , we get the surprising result that the limit to $\frac{p}{2S}$ in this case is also given by Equation (35). Thus, the limit curve in Figure 43 has two meanings: it is the limit at which the minimum of the shear stress $\frac{\sigma_{\theta} - \sigma_r}{2}$ from residual pressures becomes equal to -S at the bore, and it is also the limit at which the bore shear stresses $\frac{\sigma_{\theta} - \sigma_r}{2}$ and $\frac{\sigma_z - \sigma_r}{2}$ become equal under the bore pressure p.

From the limit curve in Figure 43 and from Equation (35) it is found that

$$\lim_{K \to \infty} \left(\frac{p}{2S}\right) = 1 \tag{36}$$

Thus, the maximum possible pressure in a multiring container designed on the basis of static shear strength using ductile materials is p = 2S. For a ductile material with a tensile yield strength of 2S = 180,000 psi, this means that the maximum pressure is limited to 180,000 psi.

Fatigue Shear Strength Analysis

The optimum design of a multiring container having all rings of the same material and based on fatigue shear strength is found by an analysis similar to that conducted on the basis of static shear strength. Instead of minimizing S in Equation (27), σ given by the fatigue relation, Equation (9) is minimized, i.e.,

$$\frac{\partial \sigma}{\partial k_n} = 0, n = 1, 2, \dots, N-1$$
 (37)

The stresses S_r and S_m needed in expressing σ in Equation (9) are given by Equations (16) and (17).

The results of carrying out the analysis are:

$$p_{n} = p_{n-1} + \frac{p(k_{n}^{2}-1)}{4(K^{2}-1)} k_{n+1}^{2} k_{n+2}^{2} \dots k_{N}^{2} - \frac{\sigma(k_{n}^{2}-1)}{2k_{n}^{2}}, n = 1, 2, \dots, N-1$$
(38)

$$k_1 = k_2 \dots = k_N \tag{39}$$

$$\sigma = \frac{5}{2N} p \frac{K^2/N}{K^2/N-1}$$
(40)

The q_n are again given by Equation (32) and the resulting interference required is

$$\frac{\Delta n}{r_n} = \frac{5p}{2NE}$$
(41)

The result p/σ is plotted in Figure 44. The limit curve is for $S_m = 0$ in the inner cylinder and is given by

$$\lim_{K \to \infty} \left(\frac{p}{\sigma}\right) = \lim_{K \to \infty} \left(\frac{2}{3} \frac{K^2 - 1}{K^2}\right) = \frac{2}{3}$$
(42)

If a ductile material has an <u>ultimate tensile</u> strength of 210,000 psi, then Equation (42) gives a maximum pressure of 140,000 psi based upon the shear fatigue criterion.

These results on ductile materials show that higher strength materials will have to be used in order to reach the high pressures desired. Accordingly, an analysis of a multiring container with a high-strength liner is now described.

High-Strength Liner Analysis

The hoop stress σ_{θ} at the bore of the liner undergoes the greatest range in stress during a cycle of pressure. Therefore, the tensile fatigue criterion is applied to the σ_{θ} stress. The range in the σ_{θ} stress at the bore of a multi-ring container depends only upon the over-all ratio K and the bore pressure p and is independent of the number of rings, i.e.,

$$(\sigma_{\theta})_{r} = \frac{p}{2} \frac{K^{2} + 1}{K^{2} - 1}$$
(43)

[Equation (43) is found from Equation (13b) for $r = r_0$, $r_n = r_N$, and $k_n = K$.]

In the formulation of the tensile fatigue criterion the parameter α_r has been defined by Equation (10a). Thus, from Equations (10a) and (43) it is found that

$$\frac{\mathbf{p}}{\sigma_1} = 2\alpha_r \frac{\mathbf{K}^2 - 1}{\mathbf{K}^2 + 1} , \quad \sigma_1 \leq \sigma_u$$
(44)

where σ_u is the ultimate tensile stress of the liner. The ratio p/σ_1 is plotted in Figure 45 for various K and α_r .

The fatigue data at room temperature of high-strength steels ($\sigma_u \leq 300,000 \text{ psi}$) listed previously in Tables XLII, XLIII, and XLIV are generally for $\alpha_r \leq 0.5$ for lifetimes of 10⁴ and greater. Hence, it is concluded that the maximum repeated pressure possible in a multiring container with a liner of $\sigma_u = 300,000$ psi is approximately 300,000 psi if appreciable fatigue life is required. This conclusion presupposes that the outer components can also be designed to withstand the required interface pressure and that sufficient precompression can be provided in the liner so that $\alpha_r = 0.5$ can be expected to give up to 10^4 cycles life. This is investigated next.



FIGURE 43. MAXIMUM PRESSURE-TO-STRENGTH RATIO, p/2S, IN MULTIRING CONTAINER DESIGNED ON BASIS OF STATIC-SHEAR STRENGTH

Each ring is assumed to be of the same ductile material.



FIGURE 44. MAXIMUM PRESSURE-TO-STRENGTH RATIO, p/o, IN MULTIRING CONTAINER DESIGNED ON BASIS OF FATIGUE SHEAR STRENGTH

Each ring is assumed to be of the same ductile material.

The stress range parameter α_r depends on the mean stress parameter α_m . The mean stress depends not only on the bore pressure p but on the interface pressures p_1 and q_1 between the liner and the second cylinder. The magnitudes of p_1 and q_1 that are possible depend upon the geometry and strength of the outer cylinders.

The outer rings are assumed to be all made of the same ductile material. Conducting a fatigue-shear-strength analysis of a multiring container having a pressure fluctuating between q_1 and p_1 , we find from a method similar to that used in arriving at Equation (39) (using Equation (37) for n = 2, 3, ..., N-1), that in this case also the optimum design has

$$k_2 = k_3 = \dots = k_n$$
 (45)

Calculating the mean stress σ_m at the bore of the liner, equating $\alpha_m \sigma_1$ to σ_m from Equation (10b), substituting for q_1 from Equation (32), eliminating σ_1 by use of Equation (44), and solving for p_1 , one finds

$$p_{1} = \frac{p}{K^{2} - 1} \left[\frac{K^{2} - k_{1}^{2}}{k_{1}^{2}} + \frac{(K^{2} + 1)}{4} - \frac{(k_{1}^{2} - 1)}{k_{1}^{2}} - \frac{(\alpha_{r} - \alpha_{m})}{\alpha_{r}} \right]$$
(46)

The other interface pressures p_n , $n \ge 2$ are again given by Equation (38). Eliminating the pressures p_1 and p_n , $n \ge 2$ from Equations (46) and (38), and solving for the pressure-to-strength ratio p/σ , one gets

$$\frac{p}{\sigma} = \frac{2(K^2 - 1) (k_n^2 - 1) (N - 1) k_1^2 \alpha_r}{k_n^2 [5(K^2 - k_1^2) \alpha_r + (\alpha_r - \alpha_m) (K^2 + 1) (k_1^2 - 1)]}$$
(47)

The k_n, $n \ge 2$ in Equation (47) are equal as shown by Equation (45). Whereas, p/σ_1 depended only upon α_r and K (Equation (44)), p/σ depends on N, k_n, and α_m in addition.

The ratio p/σ can also be limited by the requirement on Relations (7) and (9) that the mean shear stress S_m in Cylinder 2 at r_1 obeys the relation $S_m \ge 0$. $S_m \ge 0$ gives

$$\left(\frac{p}{\sigma}\right)_{\text{limit}} = \frac{2}{3} \frac{(K^2 - 1)}{K^2} k_1^2 \qquad (48)$$

As is evident from the limit curves plotted in Figure 46, the pressure limit for the outer rings can be increased by increasing k_1 . This means that the liner has a great effect on p. The strength of the liner, σ_1 , influences p in Equation (44). The size of the liner, k_1 , limits p in Equation (48).

Whether or not p/σ can be allowed as high as the limit, however, depends on the other factors N, α_r , K, etc., as shown by Equation (47). This dependence is rather complicated. Example curves of p/σ are plotted in Figures 47 and 48 for $\alpha_r = 0.5$ and $\alpha_m = -0.5$. As shown by these curves p/σ increases with N and also increases with k_1 for N = 5, K ≥ 6.5 .



FIGURE 45. MAXIMUM PRESSURE-TO-STRENGTH RATIO, p/σ_1 , IN MULTIRING CONTAINER WITH HIGH-STRENGTH LINER BASED ON THE FATIGUE TENSILE STRENGTH OF LINER



FIGURE 46. LIMIT TO MAXIMUM PRESSURE-TO-STRENGTH RATIO, p/o, IN MULTIRING CONTAINER WITH HIGH-STRENGTH LINER BASED ON SHEAR FATIGUE STRENGTH OF THE OUTER RINGS



FIGURE 47. INFLUENCE OF NUMBER OF RINGS ON MAXIMUM PRESSURE-TO-STRENGTH RATIO, $_{\rm P}/\sigma_{\rm r}$ IN MULTIRING CONTAINER WITH HIGH-STRENGTH LINER



FIGURE 48. INFLUENCE OF LINER SIZE ON MAXIMUM PRESSURE-TO-STRENGTH RATIO, p/o, IN MULTIRING CONTAINER WITH HIGH-STRENGTH LINER

Suppose p = 300,000 psi as determined from Equation (44) for $\alpha_r = 0.5$ and $\sigma_1 = 300,000$ psi. Then from Figure 48, K must be 9.0 for $k_1 = 1.75$ and N = 5 if $\sigma = 210,000$. Thus, the multiring cylinder must be quite large in size to support maximum repeated pressures.

The interferences Δ_n and residual pressures q_n have yet to be determined for the multiring container. Since the liner and the outer rings are assumed to be made from two different materials, thermal expansions must be included in the interference calculations. It is assumed that no thermal gradients exist; all components reach the same temperatures uniformly. Therefore, the interference required between the liner and the second cylinder is expressed as

$$\frac{\Delta_1}{r_1} = -\frac{u_1(r_1)}{r_1} + \frac{u_2(r_1)}{r_1} - \alpha_1 \Delta T + \alpha_2 \Delta T$$
(49)

where

 Δ_1 = manufactured interference

- $u_1(r)$ = radial deformation of liner at r_1 due to residual pressure q_1 at r_1
- $u_2(r_1) = radial deformation of Cylinder 2 at <math>r_1$ due to residual pressures q_1 at r_1 and q_2 at r_2
- α = coefficient of thermal expansion at temperature

 ΔT = temperature change from room temperature.

The interferences \triangle_n required between the outer cylinders is again given by Equation (33) for $n \ge 2$. The residual pressures q_n needed in calculating the \triangle_n are found from Equation (32) for p_n given by Equations (46) and (38). In the calculation of the u_n from Equation (14a), the values of the moduli of elasticity, E_n at temperature should be used.

The container designed for use at temperature will have residual pressures q_n^* at room temperature different from the q_n necessary at temperature. The q_n^* are found as follows: the u_n^* are first expressed in terms of q_n^* from Equation (14a) using the values of E_n at room temperature, the Δ_n are expressed in terms of the u_n^* from Equations (49) and (33) for $\Delta T = 0$. This procedure gives the following system of equations in the q_n^* :

$$A_{11}q_{1}^{*} + A_{12}q_{2}^{*} = E_{2} \frac{\Delta_{1}}{r_{1}}$$

$$nn - 1^{q}n - 1^{*} + A_{nn}q_{n}^{*} + A_{nn+1}q_{n+1}^{*} = E_{n}\frac{\Delta_{n}}{r_{n}}, n = 2, 3, \dots, N-1$$
(50a, b, ...)

where

A

$$A_{11} = \frac{k_2^2 + 1}{k_2^2 - 1} + \nu + \frac{E_2}{E_1} \left(\frac{k_1^2 + 1}{k_1^2 - 1} - \nu \right), \quad A_{nn-1} = \frac{-2}{k_n^2 - 1}, \quad A_{12} = \frac{-2k_2^2}{k_2^2 - 1},$$

$$A_{nn} = \frac{k_n^2 + 1}{k_n^2 - 1} + \frac{k_{n+1}^2 + 1}{k_{n+1}^2 - 1} = 2\frac{k_n^2 + 1}{k_n^2 - 1} \qquad A_{nn+1} = \frac{-2k_{n+1}^2}{k_{n+1}^2 - 1} = -2\frac{k_n^2}{k_n^2 - 1}$$

and where \triangle_1 and the \triangle_n , $n \ge 2$ have been previously calculated for $\triangle T \ne 0$. There are N-1 linear equations (50a,b,...) in N-1 unknowns q_n , n = 1, 2, ..., N-1 ($Q_N = 0$). These are easily solved by matrix solution on the computer.

Having calculated the residual pressures q_n^* at room temperature the residual stresses can be calculated from Equations (13a-c). These residual stresses can then be checked in order to ensure that they are within tolerated bounds. Examples of such calculations are described later when specific designs are considered. Next, the ring-segment container is considered.

Ring-Segment Container

A ring-segment container has been shown in Figure 39b. For this design, the equilibrium requirement, Equation (21), relates p_1 and p_2 . Under shrink-fit it is assumed that the segments just barely contact each other, i.e., the segments carry no hoop stress. (If the segments were in strong contact with each other, they would act like a complete ring, i.e., they would carry compressive hoop stress, and the distinction between a ring-segment container and a multiring container would be lost.) Thus, the same equilibrium requirement applies to the residual pressures q_1 and q_2 . This requirement is

$$p = p_1/k_2, \quad q = q_1/k_2$$
 (51a, b)

+ $\alpha_3 \triangle Tr_2 - \alpha_1 \triangle Tr_1$

(52)

In order to determine the pressures p_1 and q_1 the following radial deformation equation is formulated:

$$u_2(r_2) - u_2(r_1) + \Delta_{12} + \alpha_2 \Delta T (r_2 - r_1) = u_3(r_2) - u_1(r_1)$$

where

 Δ_{12} = the manufactured interference defined as the amount $(r_2 - r_1)$ of the segments exceeds $(r_2 - r_1)$ of the cylinders

 $u_n(r_m)$ = the radial deformation of component n at r_m due to pressure p_n or q_n at r_n and p_{n-1} or q_{n-1} at r_{n-1}

 α_n = thermal coefficient of expansion of component n

 ΔT = temperature change from room temperature.

If the elasticity solutions, Equations (14a) and (19a), for the u_n , and Equation (51a) for p_2 are substituted into Equation (52) and the resulting expression solved for p_1 , then there results

$$p_{1} = \frac{1}{g} \left\{ \frac{2p}{k_{1}^{2}-1} + 2 \frac{E_{1}}{E} \frac{k_{2}k_{3}^{2}p_{3}}{(k_{3}^{2}-1)} + \frac{E_{1}\Delta_{12}}{r_{1}} - \Delta TE_{1} \left[k_{2}(\alpha_{3} - \alpha_{2}) + (\alpha_{2} - \alpha_{1}) \right] \right\}$$
(53)

where

$$g = \frac{k_1^2 + 1}{k_1^2 - 1} + \frac{E_1}{E_2} \left[\frac{2(k_2 - 1)}{k_2 + 1} + \frac{M_1}{\beta_1} \left((f_3(r_1) - k_2 f_3(r_2)) \right] + \frac{E_1}{E_3} \left[\frac{k_3^2 + 1}{k_3^2 - 1} + \nu \right] - \nu$$
(54)

The E_n are the moduli of elasticity at temperature. The parameters M_1 and β_1 and the function $f_3(r)$ have been defined previously in reference to Equations (19a, b). The procedure for finding q_1 is the same as that for finding p_1 except that p = 0 and q_3 replaces p_3 , i.e.,

$$q_{1} = \frac{1}{g} \left\{ 2 \frac{E_{1}}{E} \frac{k_{2}k_{3}^{2}q_{3}}{(k_{3}^{2}-1)} + \frac{E_{1}\Delta_{12}}{r_{1}} - \Delta TE_{1} \left[k_{2}(\alpha_{3}-\alpha_{2}) + (\alpha_{2}-\alpha_{1}) \right] \right\}$$
(55)

A fatigue analysis of the high-strength liner is now conducted. The range in the hoop stress at the bore is:

$$(\sigma_{\theta})_{r} = \frac{(\sigma_{\theta})_{\max} - (\sigma_{\theta})_{\min}}{2} = \frac{p}{2} \frac{(k_{1}^{2} + 1)}{(k_{1}^{2} - 1)} - \frac{(p_{1} - q_{1})k_{1}^{2}}{k_{1}^{2} - 1}$$
(56)

where Equation (13a) has been used. (p_1-q_1) is given by Equation (55), but an expression for (q_3-p_3) is needed before Equation (56) can be used to solve for p. The expression for (p_3-q_3) is obtained from Equation (32) with (p_2-q_2) replacing p and with $k_3^2k_4^2...k_N^2$ replacing K² in Equation (31). There results

$$q_{n} = p_{n} - \frac{(p_{2}-q_{2}) (k_{n+1}^{2} k_{n+2}^{2} \dots k_{N}^{2} - 1)}{(k_{3}^{2} k_{4}^{2} \dots k_{N}^{2} - 1)}, n \ge 3$$
(57)

Substituting for (q_3-p_3) from Equation (57) into (55), then substituting for (p_1-q_1) from Equation (55) into (56), equating $(\sigma_{\theta})_r$ and $\alpha_r \sigma_l$ from Definition (10a), and solving for p/σ_1 , one obtains

$$\frac{p}{\sigma_{1}} = \frac{2\alpha_{r}(k_{1}^{2}-1)^{2}(g-h)}{\left[(g-h)(k_{1}^{4}-1)-4k_{1}^{2}\right]}$$
(58)

where

$$=\frac{2E_1 k_n^2 (k_n^{2(N-3)}-1)}{E_3 (k_n^{2(N-2)}-1)}$$

(59)

h

 $(k_3 = k_4 = ... = k_n \text{ for the outer cylinders as shown by Equation (45). Therefore, <math>k_3^2 k_4^2 \dots k_N^2 = k_n^{2(N-2)}$ in the expression for h.)

It is easily shown that (g-h) is independent of N, the number of components. Therefore, p/σ_1 given by Equation (58) is independent of N. However, p/σ_1 is dependent upon k_1 whereas for the multiring container it was not as previously shown by Equation (44). This dependence is also shown in Figure 49. From this figure it is evident that the ringsegment container cannot withstand as great a pressure as the multiring container if the overall size is the same. This result is believed due to the fact that the segments do not offer any support to the liner – they are "floating" members between the liner and the third component, another ring. The effect is more pronounced as the segment size is increased. This is shown in Figure 50 where it is seen that the pressure decreases with increasing segment size.

The detrimental effect of insufficient segment support to the liner can be reduced by using a high modulus material, tungsten carbide, for the segment material. This is shown in Figure 51. However, the improvement is not sufficient enough to increase the pressure capability of the ring-segment container to that of the multiring container. This conclusion is based on results for various wall ratios.

The fatigue analysis of the outer ductile cylinders is conducted in the same manner as it was done for the multiring container, except now the component numbers are n = 3, 4, ..., N. The result is

$$\frac{p}{\sigma} = \frac{\alpha_{r} (k_{n}^{2} - 1) (N - 2)}{k_{n}^{2} \left[\frac{(\alpha_{r} - \alpha_{m})}{2} \frac{(k_{1}^{2} + 1)}{k_{2} k_{1}^{2}} + \frac{(3\alpha_{r} + 2\alpha_{m})}{k_{2} (k_{1}^{2} - 1) (g - h)} \right]}$$
(60)

This result is plotted in Figure 52, which shows the effect of increasing k_1 and comparison with the multiring container. Although p/σ can be increased by use of segments, the ring-segment container has the limitation of lower p/σ_1 as shown before in Figures 49 and 50.

The effect on p/σ of increasing the segment modulus was also investigated. However, the effects were found to be insignificant.

Ring-Fluid-Segment Container

The ring-fluid-segment container is illustrated in Figure 39c. This container is a combination of a ring-segment container for the inner part and a multiring container for the outer part. All of the equations derived for the multiring container can be used



FIGURE 49. COMPARISON OF MULTIRING CONTAINER WITH RING-SEGMENT CONTAINER FOR VARIOUS \mathbf{k}_1

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FIGURE 50. COMPARISON OF MULTIRING CONTAINER WITH RING-SEGMENT CONTAINER FOR VARIOUS SEGMENT WALL RATIOS

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FIGURE 51. EFFECT OF ELASTIC MODULUS OF SEGMENTS ON PRESSURE-TO-STRENGTH RATIO, p/σ_1 , FOR THE RING-SEGMENT CONTAINER



FIGURE 52. EFFECT OF LINER SIZE ON PRESSURE-TO-STRENGTH RATIO, p/σ , FOR RING-SEGMENT CONTAINER

for the outer part. For the inner part, Equations (51a, b), (52), (53), (54), and (55) apply. The latter equation applies with $q_3 = 0$. Equation (56) is valid and can be used to find p/σ_1 for the liner. [Equation (56) is not needed since p_3 is given.] Solving for p/σ_1 , one finds

$$\frac{p}{\sigma_{1}} = \frac{\alpha_{r} (k_{1}^{2}-1)}{\left[\frac{k_{1}^{2}+1}{2} - \frac{2}{g} \frac{k_{1}^{2}}{(k_{1}^{2}-1)} - 2 \frac{E_{1}}{E_{3}} \frac{p_{3}}{p} \frac{k_{1}^{2}k_{2}k_{3}^{2}}{g(k_{3}^{2}-1)}\right]$$
(61)

This equation shows that an increase in p_3/p gives an increase in p/σ_1 .

Let σ_3 be the ultimate tensile strength of component 3, the outer cylinder of the inner part of the ring-fluid-segment container. If fatigue relation, Equation (9) is used for this cylinder, then there results

$$\sigma_3 = \frac{k_3^2}{k_2^2 - 1} \left[\frac{5}{2} (p_2 - p_3) - \frac{1}{2} q_2 \right]$$
(62)

The pressures p_2 and q_2 are related to p_1 and q_1 via Equations (51a, b). p_1 and q_1 are related by Equation (55) with $q_3 \equiv 0$. One other equation involving p_1 and q_1 is needed which is found from the Definition (10b) for the parameter α_m , i.e.,

$$\alpha_{m}\sigma_{1} = \sigma_{m} = \frac{(\sigma_{\theta})_{max} + (\sigma_{\theta})_{min}}{2} = \frac{p}{2} \frac{k_{1}^{2} + 1}{k_{1}^{2} - 1} - \frac{(p_{1} + q_{1})}{k_{1}^{2} - 1} k_{1}^{2}$$

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Solving for p_1 and q_1 , finding p_2 and q_2 , substituting into Equation (62), and solving for p/σ_3 , one obtains

$$\frac{p}{\sigma_3} = \frac{(k_3^2 - 1)}{k_3^2 \left\{ \frac{2}{k_2} \frac{q_1}{p} + \frac{5}{g(k_1^2 - 1) k_2} + \frac{5}{2} \frac{p_3}{p} \left[\frac{2E_1}{gE_2} \frac{k_3^2}{(k_3^2 - 1)} - 1 \right] \right\}}$$
(63)

where

$$\frac{q_1}{p} = \frac{(\alpha_r - \alpha_m)}{2} \frac{(k_1^2 - 1)}{k_1^2} \frac{\sigma_1}{p}$$

The pressure-to-strength ratios p/σ_1 and p/σ_3 are plotted in Figures 53 and 54 as a function of segment size k₂ and wall ratio K' for k₁ = 1.1, p₃/p = 0.2, $\alpha_r = 0.5$, and $\alpha_m = -0.5$. The pressure-to-strength ratios increase with K' or equivalently with k₃, since K' = k₁k₂k₃. The behavior shown for k₁ = 1.1 is the same as that found previously for the ring-segment container; i.e., p/σ_3 increases with increasing k₂, but p/σ_1 decreases. However, if k₁ is increased to 1.5 from 1.1, then p/σ_1 also increases with Bug bistiens (propositions) [generated (provide the meridian provided the structure of the started for a started started for the started started for the started started started started for the started starte



FIGURE 53. EFFECT OF SEGMENT SIZE ON THE PRESSURE-TO-STRENGTH RATIO, p/σ_1 , FOR THE RING-FLUID-SEGMENT CONTAINER





k2 for large K' as shown in Figure 55. p/σ_3 continues to increase with k₂ as shown in Figure 56. Thus, both p/σ_1 and p/σ_3 increase with large K' for k₂ = 2.0 and k₁ = 1.5. For values of k₂ between 2.0 and 4.0, however, computer calculations show that p/σ_1 and p/σ_3 first continue to increase and then decrease.

The pressure-to-strength ratios can also be increased by increasing the support pressure p₃. This is shown in Figure 57. With the high ratios shown, it is theoretically possible to have bore pressures as high as 1,000,000 psi in ring-fluid-segment container. However, <u>practicable</u> limitations regarding excessive interference and size requirements, which are discussed later, considerably reduce the pressure capability of this design.

The interferences and residual pressures for outer and inner parts of the ringfluid-segment container can be calculated using the analysis derived previously for the multiring container and the ring-segment container, respectively.

Pin-Segment Container

The analysis of the pin-segment container, shown in Figure 39d, also assumes a high-strength liner. It is also assumed that any manufactured interference is taken up during assembly by slack between pins and holes. Therefore, the residual pressure, q_1 , between liner and segments is zero at room temperature and nonzero at temperature only if the coefficient of thermal expansion of the liner, α_1 , is greater than that of the segments, α_2 . In this analysis, it is assumed that $\alpha_1 \ge \alpha_2$.

The following radial deformation equation must be satisfied:

$$u_1(r_1) + \alpha_1 \Delta Tr_1 = u_2(r_1) + \alpha_2 \Delta Tr_2$$
(64)

where

 $u_1(r_1) =$ the radial deformation of the liner at r_1 due to p at r_0 and p_1 at r_1 when $p \neq 0$, and due to q_1 at r_1 when p = 0

 $u_2(r_1) =$ the radial deformation of the segments at r_1 due to p_1 or q_1 at r_1 and the pin loading at r_2 .

Substituting into Equation (64), Equations (14a) and (23a) for u_1 and u_2 , and solving for p_1 , one gets

$$p_{1} = \frac{1}{g_{2}} \left[\frac{2p}{k_{1}^{2}-1} + E_{1} \triangle T (\alpha_{1} - k_{2}\alpha_{2}) \right]$$
(65)



FIGURE 55. EFFECT OF SEGMENT SIZE ON THE PRESSURE-TO-STRENGTH RATIO, p/σ_1 , FOR THE RING-FLUID-SEGMENT CONTAINER



FIGURE 56. EFFECT OF SEGMENT SIZE ON THE PRESSURE-TO-STRENGTH RATIO, p/σ_3 , FOR THE RING-FLUID-SEGMENT CONTAINER

where

$$g_{2} = \frac{E_{1}}{E_{2}} \left[\frac{k_{2}^{2} + 1}{k_{2}^{2} - 1} + \nu + \frac{M_{2}f_{3}(r_{1})}{\beta_{1}} + E_{2} \frac{G_{2}}{r_{1}} + g_{m4}(r_{1}) \right] + \frac{k_{1}^{2} + 1}{k_{1}^{2} - 1} - \nu \quad .$$
(66)

Similarly, q1 is found if p is taken as zero; i.e.,

$$q_{1} = \frac{E_{1} \triangle T (\alpha_{1} - k_{2} \alpha_{2})}{g_{2}}$$
 (67)

Formulating the range in hoop stress $(\sigma_{\theta})_r$ at the bore (Equation (56) and using the definition $\alpha_r \sigma_1 = (\sigma_{\theta})_r$, we get the following expression for p/σ_1 :

$$\frac{p}{\sigma_1} = \frac{2\alpha_r (k_1^2 - 1)^2 g_2}{\left[g_2 (k_1^4 - 1) - 4k_1^2\right]}$$
(68)

[Equation (68) is identical in form to Equation (58).]

The pressure-to-strength ratio p/σ_1 is plotted in Figure 58. Comparing this figure with Figure 45 for the multiring container with $\alpha_r = 0.5$, it is evident that both containers have the same limit $p/\sigma_1 \rightarrow 1$ for large wall ratios. However, $\alpha_r = 0.5$ is possible only if $\alpha_m \leq 0$ as shown in Figure 42. Actually, $\alpha_m = +0.5$ is likely in the pinsegment container if $\alpha_r = 0.5$ because any interference is expected to be lost in taking up slack between pins and holes. In this case, then, $\alpha_r = 0.5$ would mean only one cycle life whereas $\alpha_r = 0.5$ means 10^4 to 10^5 cycles life in the multiring container. If this assembly problem could be eliminated by careful machining and selective fitting of pins, then theoretically with sufficient compressive prestress, the p/σ_1 ratio of the pinsement container could be made to approach that of the multiring container.

Since no prestress has been assumed for the pin-segment container, $\alpha_r = \alpha_m = 0.35$ for 10^4 to 10^5 cycles as shown by Figure 42. For $\alpha_r = 0.35$, it is found that p/σ_1 is limited to 0.7 at best. Therefore, the maximum pressure in the pin-segment container is p = 0.7 (300,000) = 210,000 psi for 10^4 to 10^5 cycles life.

The stresses in the segments have not yet been considered. High stresses develop around the pin holes. These too limit the pressure in the pin-segment container. Analysis of the stresses in the segments is described in Appendix I. For the purpose of estimating stresses in the segments the interface pressure p_1 is needed. Therefore, plots of p_1/p are provided in Figure 59. It is evident that the interface pressure p_1 is appreciably less than the bore pressure p_1 especially for large k_1 and small k_2 .

The pins are analyzed in Appendix II. In order to carry the pressure loading p_1 , it is found that the pin-to-segment-diameter ratio must be



FIGURE 57. EFFECT OF SUPPORT PRESSURE, p₃, ON BORE PRESSURE, p, CAPABILITY FOR THE RING-FLUID-SEGMENT CONTAINER

 $\alpha_r = 0.5, \ \alpha_m = -0.5$ $k_1 = 1.5, \ k_2 = 2.0.$



FIGURE 58. MAXIMUM PRESSURE-TO-STRENGTH RATIO, p/σ_1 , FOR THE PIN-SEGMENT CONTAINER



FIGURE 59. RATIO OF INTERFACE PRESSURE BETWEEN SEGMENTS AND LINER TO BORE PRESSURE FOR THE PIN-SEGMENT CONTAINER

$$\frac{d}{2r_1} = \frac{8}{3} \frac{t}{d} \frac{p_1}{\tau}$$

where

d = pin diameter,

 $2r_1 = inside segment diameter,$

t = segment thickness,

 τ = maximum shear stress in pin.

Strip-Wound Container

An analysis was not conducted for the strip-wound container, because it is possible to estimate its relative strength based upon the results of the analysis of the multiring container. The strip-wound (wire-wrapped) cylinder uses basically the same principle as the multiring container. It has a cylindrical inner cylinder, the liner, under prestress, but the prestress in the liner is provided by wrapping strips or wire under tension onto the liner.

To estimate the pressure-to-strength ratio of the strip-wound vessel it is assumed that it behaves overall as a thick cylinder under internal pressure after the strip has been wound on. Referring to Equation (44), we see that the pressure-to-strength ratio p/σ_1 depends only on the overall wall ratio K and α_r the stress-range parameter for the liner material. If K for the strip-wound vessel is taken as the ratio of the outside diameter of the last strip layer to the inner bore diameter, then Equation (44) can be used to estimate its pressure capability. Therefore, it may be concluded that the stripwound container has a maximum pressure equal that of the multiring container. However, unknown local stress concentrations and contact conditions between strips may be detrimental in the strip-wound design. Because of these possible disadvantages and no better pressure capability than the multiring container, detailed analysis of the stripwound vessel is not warranted. However, the strip-wound design does offer advantages in producibility of large-diameter containers as pointed out later in the "Design Requirements" section of this report.

Controlled Fluid-Fill, Multiring Container

A controlled fluid-fill container, shown in Figure 60, has been proposed by Berman⁽⁴²⁾. All the rings are assumed to be made of the same ductile material and a shear-strength criterion applies. Like the ring-segment-fluid container, this container also uses the fluid-pressure support principle. The advantage of this design is that under static applications the residual-stress limitation (the limit curve in Figure 43) can be overcome by controlling the pressures p_n ; i.e., the pressures, p_n , can be reduced to zero as the bore pressure, p, is reduced to zero. There are no shrink fits, so there are no residual stresses. Berman's analysis was based upon static strength. A similar analysis is now conducted based on fatigue strength.



FIGURE 60. CONTROLLED FLUID-FILL CYLINDRICAL-LAYERED CONTAINER [REFERENCE (42)]

In order that each ring may have the same shear stress under static pressure, Berman finds that the same relation, Equation (30) [first found by Manning⁽⁵⁾], applies for the controlled fluid-fill container that also applies for the multiring container designed for static shear strength. If this result is used in a shear fatigue analysis (assuming ductile materials), then Equation (30) can be interpreted as the maximum shear stress developed during a cycle of pressure, i.e.,

$$(S)_{\max} = \frac{p}{N} \frac{K^{2/N}}{(K^{2/N} - 1)}$$
(70)

If the pressures p_n are reduced to zero, then the minimum shear stress during a cycle of pressure is zero. Therefore, the semirange and mean shear stresses are equal,

$$S_{m} = S_{r} = \frac{pK^{2/N}}{2N(K^{2/N}-1)}$$
 (71a, b)

where S_m and S_r are defined in Equations (6a, b).

If Equation (71a, b) are substituted into the fatigue relation, Equation (9), there results

$$\sigma = \frac{5p}{2N} \frac{K^2/N}{(K^2/N_{-1})}$$
(72)

It is surprising that this result, Equation (72), is the same as Equation (40) plotted in Figure 44, the result of the shrink-fit analysis, except now the limit Equation (42) no longer applies. Therefore, now p/σ can be made as large as desired simply by increasing N. The only problem is that the required N or K may be too large to be practical. For example, assume $\sigma = 150,000$ psi (ultimate strength of a ductile steel), N = 8 and K = 16. Calculating p we find that p = 240,000 psi. Thus, it is concluded that for fatigue applications under high pressure the controlled-fluid-fill, multiring container becomes too large to be practical. Eight rings also means there are seven annuli under fluctuating pressures. (The magnitudes of these pressures are all different and are given by an equation similar to Equation (38).) Design of mechanical apparatus to supply and control all these pressures presents practical difficulties also.

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ANALYSIS OF RING FLUID RING CONTAINERS FOR HIGH PRESSURE

A high-pressure-container design was suggested in Interim Report $IV^{(21)}$ which derives the benefit of both shrink-fit and fluid-pressure support. This design is shown in Figure 40. It is composed of two multiring units and therefore avoids the numerous difficulties encountered in segmented designs. Analyses of this advanced container design are described in this section. The analyses for calculating maximum pressure capability, residual stress, and required shrink-fit interferences were programmed for calculation on Battelle's CDC 3400 and 6400 computers.

Generalized Fatigue Criteria

In the earlier analyses, two fatigue criteria were used for either high-strength liner steels or for ductile outer cylinders. These were a tensile-strength criterion and a shear-strength criterion repectively. These criteria were postulated for pressurevessel stress conditons. The fatigue data available in the literature were used to determine the criterion for failure. Only uniaxial data could be found on high-strength steels. Some triaxial fatigue data from pulsating fluid-pressure tests were available on lowstrength steels. ⁽³⁵⁾

In a general design of a multiring container, different steels with different fatigue behavior may be used to advantage for each ring. Since no definite fatigue data are available at this time on the biaxial or triaxial fatigue of high-strength steels in particular, generalized fatigue criteria with arbitrary coefficients are formulated here on both a tensile-strength and a shear-strength basis. (For example, it may be that a highstrength brittle steel will fail in a ductile manner when subjected to high bore pressures in a container.) These generalized fatigue relations are as follows:

$$A_{n} (\sigma_{\theta})_{r} + B_{n} (\sigma_{\theta})_{m} = \sigma_{n} , \qquad (73a, b)$$
$$A_{n} S_{r} + B_{n} S_{m} = \sigma_{n} , \qquad (73a, b)$$

where

or

 A_n , B_n are coefficients describing the material of ring number n, subscript r denotes the semirange stress component, subscript m denotes the mean stress component, and σ_n is the tensile strength of ring number n.

The linear relations (73a, b) can be used to describe in a stepwise manner, nonlinear behavior as illustrated by the semirange, mean-shear-stress plot in Figure 61. (The constant coefficients A_n and B_n in (73a) are related to the variable parameters α_r and α_m defined earlier as follows: $A_n = \frac{1}{\alpha_r}$ for $\alpha_m = 0$, $B_n = \frac{1}{\alpha_m}$ for $\alpha_r = 0$.) The shear fatigue relation



FIGURE 61. GENERALIZED FATIGUE RELATION IN TERMS OF SHEAR STRESSES



FIGURE 62. SHEAR-YIELD- AND SHEAR-FATIGUE-STRENGTH RELATIONS

$$3S_r + 2S_m = \sigma$$
, where $\sigma \le \sigma_u$, for 10^6 cycles life (74)

[Equation (9) in the previous analyses], must be limited by the yield strength, σ_y , for large mean stresses as shown in Figure 62, i.e.

$$2S_{\max} = 2S_r + 2S_m \le \sigma_y \tag{75}$$

A conservative shear-fatigue relation is the following:

$$\left(\frac{3\sigma_y}{\sigma_u}\right)S_r + 2S_m = \sigma_y$$
, for 10⁶ cycles life (76)

Relation (76) is also shown in Figure 62. [The coefficient $A_n = 3$ in Equations (74) and (76) is taken from data in Reference (35) as indicated earlier on page 164.]

The significance of the limit $S_m = 0$ [used in conjunction with Equation (7) on page 163] is now pointed out. S_m at the bore is related to $(\sigma_{\theta})_m$ as follows:

$$S_{m} = \frac{(\sigma_{\theta})_{m}}{2} + \frac{(p_{0} - q_{0})}{4} = \frac{(\sigma_{\theta})_{m}}{2} + \frac{p_{0}}{4} \text{ for } q_{0} = 0 .$$

Thus,

$$(\sigma_{\theta})_{m} = -\frac{p_{0}}{2} \text{ for } S_{m} = 0 \quad .$$

$$(77)$$

For a multiring container it was found that $\left((p_0)_{\max} \approx \sigma_u \text{ for } \alpha_r = \frac{(\sigma_\theta)_r}{\sigma_u} = 0.5, \alpha_m = 0.5\right)$

 $\frac{(\sigma_{\theta})_{m}}{\sigma_{u}} = -0.5 \text{ for } 10^{4} - 10^{5} \text{ cycles life}$. Therefore, the maximum tensile strength fatigue criterion with $\alpha_{r} = 0.5$, $\alpha_{m} = -0.5$ is equivalent to $S_{m} = 0$ for the shear strength criterion.

Coefficients A_n and B_n in Equation (73a) are now calculated for the tensile criterion postulated for high-strength steels ($\sigma_u \ge 250,000$ psi) from the fatigue data given in Table XLII and XLIII. These data are as follows in terms of α_r and α_m :

	Semirange F	Parameter, α_r
Fatigue Life, cycles	for $\alpha_m = 0$	for $\alpha_r = \alpha_m$
$10^{4} - 10^{5}$	0.50	0.35
106-107	0.35	0.25

Thus, for $0 \le \alpha_m \le \alpha_r$ (zero to a positive mean stress) the coefficients A_n and B_n are calculated to be:

Fatigue Life, cycles	An	Bn
$10^{4} - 10^{5}$	2.00	0.86
106-107	2.86	1.14

For, $-\alpha_r \le \alpha_m \le 0$, in leiu of actual data, the fatigue relation (73a) is assumed to be horizontal (Figure 61), i.e., $B_n = 0$ with $A_n = 2.00$ and $A_n = 2.86$ for 10^4 - 10^5 and 10^6 - 10^7 cycles life, respectively.

General Analysis of Multiring Containers

A multiring container or a multiring unit of a two-unit container such as has been shown in Figure 40, is assumed to have pressures fluctuating between q_0 and p_0 in the bore and between q_N and p_N on the outside diameter. Minimum stresses during the cycle occur at pressure preloadings q_0 and q_N , and maximum stresses occur at operatingpressure loadings of p_0 and p_N . (The pressures q_N and p_N are the so called "fluidsupport pressures".) The generalized fatigue criteria (73a, b) are used. The elasticity solutions for the stress components in Equations (73a, b) are as follows:

$$(\sigma_{\theta})_{\mathbf{r}} = \frac{1}{2(k_{n}^{2} - 1)} \left[(p_{n-1} - q_{n-1})(k_{n}^{2} + 1) - 2(p_{n} - q_{n})k_{n}^{2} \right], \quad (78a, b)$$

$$(\sigma_{\theta})_{m} = \frac{1}{2(k_{n}^{2} - 1)} \left[(p_{n-1} + q_{n-1})(k_{n}^{2} + 1) - 2(p_{n} + q_{n})k_{n}^{2} \right], \quad (79a, b)$$

$$k_{n}^{2}$$

$$S_r = \frac{\kappa_n}{2(k_n^2 - 1)} [(p_{n-1} - p_n) - (q_{n-1} - q_n)]$$

The p_n are related to the q_n as follows:

$$\mathbf{p}_{\mathbf{n}} = \mathbf{q}_{\mathbf{n}} + (-\sigma_{\mathbf{rn}}) \quad , \tag{80a}$$

(80b)

where

$$\sigma_{rn} = \frac{(p_0 - q_0)}{(K^2 - 1)} (1 - k_{n+1}^2 k_{n+2}^2 \dots k_N^2)$$

$$\frac{(\mathbf{p}_{N} - \mathbf{q}_{N})}{(\mathbf{K}^{2} - 1)} (\mathbf{K}^{2} - \mathbf{k}_{n+1}^{2} \mathbf{k}_{n+2}^{2} \dots \mathbf{k}_{N}^{2}) , n = 1, 2, \dots, N-1$$

There are (2N-1) unknowns: N pressures p_n , (n = 0, 1, ..., N-1) and N-1 pressure q_n , n = 1, 2, ..., N-1. (Determining p_0 the bore pressure determines the pressure capability.) There are also (2N-1) equations: N equations from Equations (73a) or (79b) for rings n = 1, 2, ..., N and (N-1) equations from Equation (80a). Therefore a solution is tractable.

This analysis was programmed into a computer code, Program MULTIR (abbreviation for multiring), for Battelle's 3400 and 6400 CDC computers. Results are given later when specific designs are discussed. First, the influence of "fluid-support pressures" q_N and p_N is studied by considering the example of a fatigue shear strength design.

Shear-Strength Analysis of a Multiring Container

A multiring container is considered which has all rings of the same material, i.e., the same Equation (79b) is assumed valid for all rings, n = 1, 2, ..., N with $A_1 = A_2 = \dots A_N$; $B_1 = B_2 = \dots B_N$; and $\sigma_1 = \sigma_2 = \dots = \sigma_N = \sigma$. The pressure-to-strength ratio p_0/σ is derived in exactly the same manner as in Equation (42) (for the specific case $A_n = 3$, $B_n = 2$). The result is

$$\frac{p_{o}}{\sigma} = \frac{p_{N}}{\sigma} + \frac{2N}{(A_{n} + B_{n})} \frac{K^{2/N} - 1}{K^{2/N}} - \frac{(A_{n} - B_{n})}{(A_{n} + B_{n})} \frac{q_{o} - q_{N}}{\sigma}$$
(81)

Similarly, a limit is imposed such that the minimum shear stress, S_{min} , at the bore is greater than or equal to the compressive shear strength of the liner, S_c , i.e.

$$S_{\min} \ge -S_{c} = -\frac{\sigma_{c}}{2}$$
(82)

(This limit is believed to be more realistic than the limit $S_m = 0$ that was used in the earlier analysis.) Using the definition $S_{min} = -S_r + S_m$, the fatigue relation (73b) and the equation for S_r in the liner,

$$S_{r} = \frac{K^{2}}{2(K^{2} - 1)} [(p_{o} - q_{o}) - (p_{N} - q_{N})] ,$$

in the inequality (82) there results

$$\frac{\mathbf{p}_{o}}{\sigma} \leq \frac{\mathbf{K}^{2} - 1}{\mathbf{K}^{2}} \frac{\mathbf{B}_{n}}{\mathbf{A}_{n} + \mathbf{B}_{n}} \left(\sigma_{c} + \frac{2\sigma}{\mathbf{B}_{n}} \right) + (\mathbf{p}_{n} - \mathbf{q}_{n}) + \mathbf{q}_{o}$$
(83)

The pressure-to-strength ratio p_0/σ from Equation (82) and the limit (83) are sketched in Figure 63 as functions of p_N , q_N , and q_0 . The solid curve for p_0 is valid only when it is below the dashed limit curve. The support pressure, p_N , gives the most benefit as shown - both p_0 and $(p_0)_{limit}$ increase with p_N . Small amounts of pressure, q_N , are helpful if $p_0 \leq (p_0)_{limit}$. A residual bore pressure, q_0 , is detrimental - p_0 decreases with q_0 .

Considering a two-unit, multiring container, it can now be realized that it is best that the fluid support pressure also fluctuates for two reasons:

- (1) Too great a residual pressure, q_N , on the inner unit decreases its pressure capability.
- (2) The pressure, q_N , on the inner unit corresponds to the pressure, q_o , on the outer unit, which in turn decreases the pressure capability of the outer unit.

The best design in a specific case may not require that $q_N = 0$, but it will require that q_N be sufficiently small.



FIGURE 63. INFLUENCE OF PRESSURES p_N , q_N AND q_o ON THE PRESSURE CAPABILITY p_o

Comparison of the Shear and Tensile-Fatigue Criteria

A container designed on the basis of the shear-fatigue criterion will have a predicted pressure capability generally lower than that of a design based upon the tensile fatigue criterion. This is illustrated in Figure 64 for a single-ring (monoblock) container with $p_N = q_0 = q_N = 0$. The curves in Figure 64 are plots of the equations

$$p_o/\sigma_u = \frac{2}{(A_n + B_n)} \frac{K^2 - 1}{K^2 + 1}$$
 for the tensile criterion, and (84)

$$p_o/\sigma_u = \frac{2}{(A_n + B_n)} \frac{\sigma_y}{\sigma_u} \frac{K^2 - 1}{K^2}$$
 for the shear criterion (85)

For a large wall ratio (K) the shear criterion predicts lower pressure capability. For thinner walled containers, $K \leq 1.7$, the reverse is true.

For $1.4 \le K \le 2.0$ the tensile criterion and the shear criterion both predict about the same pressure capability as shown in Figure 64. This agrees with the conclusion in Reference (46) based upon experimental fatigue data of cylinders with $1.4 \le K \le 2.0$ under cyclic internal pressure. However, the shear criterion severely limits the pressure capability for large K. Thick-walled containers, multiring units, are needed to contain the high extrusion pressures and the important question arises, "Which criterion should be used"? The shear criterion curve in Figure 64 is based upon fatigue data from actual pressurized cylinder tests for low-strength ductile steels, having an ultimate tensile strength of $\sigma_u = 126,000$ psi. ⁽³⁵⁾ The tensile criterion curve, however, is based upon rotating-beam and push-pull tests of high-strength steels, $\sigma_u \ge 250,000$ psi. It has been postulated that the tensile criterion holds for the high-strength steel containers under internal pressure. Experimental verification is needed. The successful design of



FIGURE 64. PRESSURE-TO-STRENGTH RATIOS FOR SINGLE-RING CONTAINER FOR 10^{6} - 10^{7} CYCLES LIFE



FIGURE 65. COMPARISON OF THEORY AND EXPERIMENT FOR SINGLE-RING CONTAINERS

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containers for bore pressures 250,000 $\leq p_0 \leq 450,000$ psi depends upon the validity of the postulated tensile-fatigue criterion.

In Figure 65 a comparison of the theory based on the tensile criterion is made with experimental data of Reference (46). The data from Reference (46) are for 4340 steel with ultimate tensile strength $\sigma_u = 160,000$ psi. Unfortunately, the experiments were run only for lifetimes up to 10^5 cycles. The comparison, Figure 65 shows that the theory predicts a too high pressure capability in this case. If the theory derived for high-strength steels is valid for the lower strength 4340 steel, then Figure 65 indicates that a cylinder designed for 10^6 - 10^7 cycles life would actually fail earlier at 10^4 - 10^5 cycles. This may result from the detrimental effect of fluid entering voids in the materials under pressure. It is expected that large compressive prestresses from shrink-fit in multiring units will prevent this detrimental effect. This expectation needs to be investigated experimentally.

When design pressures are low enough, the more conservative shear criterion should be used. In some cases the tensile criterion can be used for an inner ring and the shear criterion for outer rings as described earlier and in Example Design 2 discussed below.

Example Designs of Containers

The design of the multiring components of the ring-fluid-ring container require not only calculation of required diameters and interferences but also due consideration of the feasibility of manufacture and assembly. Excessive size and interference requirements will render a design impracticable. Calculations are described here, using computer code MULTIR, for two example designs. The diameter and interference requirements are listed so that they may be used as a basis for judging the feasibility of manufacture. Calculations are performed for 6-inch-diameter-bore designs. A larger design, with a 15-inch-bore diameter, is then considered by scaling up the diameter and interference requirements for the smaller design.

Example Design 1

A two-unit, multiring container is analyzed based entirely on the tensile-fatiguestrength criterion. The inner unit consists of only one ring. The data for the inner unit are as follows:

wall ratio, $K = 1.5$	
nner radius, $r_0 = 3.0$ in.	
puter radius, $r_1 = 4.5$ in.	(86)
lesign tensile strength, $\sigma_1 = 300,000$ psi	
maximum internal bore pressure, $p_0 = 450,000$ psi	
minimum internal bore pressure, $q_0 = 0$.	

It is assumed that

$$(\sigma_{\theta})_{r} \cong 1/3 \sigma_{1} \tag{87}$$

(fatigue data from Tables XLII and XLIII for 10^{6} - 10^{7} cycles life), under the following conditions:

$$(\sigma_{\theta})_{\max} = 0, \ (\sigma_{\theta})_{\min} \ge -\sigma_1 \tag{88}$$

Equation (84) and the definition

$$(\sigma_{\theta})_{\min} = (\sigma_{\theta})_{\max} - 2(\sigma_{\theta})_{r}$$

require from (85) that

$$(\sigma_{\theta})_{\min} = -2/3 \sigma_1 \quad . \tag{89}$$

To obtain conditions (87-89) a fluid-support pressure varying between q_1 and p_1 is to be found. Because the inner unit consists of only one ring in this case, calculations on the computer are not necessary as they are easily performed by hand. The analysis proceeds as follows:

$$(\sigma_{\theta})_{\max} = p_{0} \frac{K^{2} + 1}{K^{2} - 1} - 2p_{1} \frac{K^{2}}{K^{2} - 1} = 0 ,$$

$$p_{1} = \frac{p_{0}}{2} \frac{K^{2} + 1}{K^{2}} = 325,000 \text{ psi} ,$$

$$(\sigma_{\theta})_{\min} = -2q_{1} \frac{K^{2}}{K^{2} - 1} = -2/3 \sigma_{1} ,$$

$$q_{1} = \frac{K^{2} - 1}{K^{2}} \frac{\sigma_{1}}{3} = 55,500 \text{ psi} .$$

$$(91)$$

Thus, it is found that the outer unit must withstand an internal pressure varying between 55,500 psi and 325,000 psi.

The computer code, MULTIR, is used for the outer-unit calculations. A 1/2-inch gap is allowed between the units for the fluid-support pressure, i.e., $r_0 = 4.50 + 0.50 = 5.00$ in. for the outer unit. The assumed data are

wall ratio, K = 4.0, number of rings, N = 3, ring radii, $r_0 = 5.0$ in., $r_1 = 7.95$ in., $r_2 = 12.61$ in., $r_3 = 20.0$ in., support pressures, $p_N = q_N = 0$, minimum bore pressure, $q_0 = 55,500$ psi, fatigue coefficients, $A_n = 2.86$, $B_n = 1.14$.

Different calculations, 1A - 1D, are performed for rings made from materials with various strengths. Results are given in Table XLV. All four calculations give results

that satisfy the requirement of maximum bore pressure of $p_0 = 325,000$ psi. The effect of varying the strength of the rings is indicated. Design 1B has the minimum required interference, $\Delta_1 = 0.0622$ in., corresponding to $\frac{\Delta_1}{r_1} = \frac{0.0622}{7.95} = 0.00782$ in. in.

				Re	sults	
	Design Tensile Strength of Rings, σ_1 , psi 1			Maximum Bore Pressure	Requ Interferen	uired ce ^(b) , in.
Design	1	2	3	for 10 ⁶ Cycles Life	Δ_1	Δ_2
1A	325,000	325,000	325,000	338, 337	0.0670	0.0739
1B	350,000	325,000	300,000	332,699	0.0622	0.0630
1C	375,000	350,000	300,000	345, 837	0.0658	0.0578
1D	400,000	350,000	300,000	351,251	0.0625	0.0578

TABLE XLV. RESULTS OF COMPUTER CODE MULTIR FOR EXAMPLE DESIGN $1^{(a)}$

(a) Based entirely on the tensile-fatigue criterion.

(b) Interferences required on the radius. Δ_1 required between rings 1 and 2, and Δ_2 required between 2 and 3.

Example Design 2

In this design the more conservative shear-fatigue-strength criterion is used for the outer (second) ring of the inner unit and for all three rings of the outer unit. The given data are:

Inner Unit

wall ratio, K = 3,

number of rings, N = 2,

radii, $r_0 = 3.00$, $r_1 = 5.1960$, $r_2 = 9.00$,

tensile strength of ring 1, $\sigma = 300,000$ psi,

yield strength of ring 2, $\sigma_y = 212,500 \text{ psi} (\sigma_y = 0.85 \sigma_u, \sigma_u = 250,000 \text{ psi}),$ fatigue coefficients,

 $A_1 = 2.86$ and $B_1 = 0$. for ring 1,

 $A_2 = 2.55$ and $B_2 = 2.0$ for ring 2,

minimum bore pressure, $q_0 = 0$,

support pressures, $p_2 = 160,000 \text{ psi}, q_2 = 0$.

Outer Unit

wall ratio, K = 4,

radii, $r_0 = 9.500$ in., $r_1 = 15.07$ in., $r_2 = 23.90$ in., $r_3 = 38.00$ in.,

number of rings, N = 3,

yield strength of rings, $\sigma_y = 255,000 \text{ psi} (\sigma_y = 0.85 \sigma_u, \sigma_u = 300,000 \text{ psi}),$ fatigue coefficients of rings, $A_n = 2.55$, $B_n = 2.00$, minimum bore pressure, $q_0 = 0$,

support pressures, $p_3 = q_3 = 0$.

The support pressure, p_2 , on the inner unit was precalculated by an analysis similar to that of Equation (90) to give $(\sigma_{\theta})_{\max} \approx 0$ at the bore.

The results of computer code MULTIR are

Inner Unit

 $p_0 = 455,832, \Delta_1 = 0.0416$ in.

Outer Unit

 $p_0 = 202,817 \text{ psi}, \Delta_1 = 0.0772 \text{ in.}, \Delta_2 = 0.1220 \text{ in.}$

The maximum allowable pressure, $p_0 = 202,817$ psi, in the outer unit represents a factor of safety of 1.33 over the required pressure of 160,000 psi.

The 6-inch-diameter-bore designs considered would require outside diameters of 40 inches and 76 inches for 325,000 psi and 455,000 psi capacities, respectively. The larger diameter requirement in the second case reflects the conservative shear-strength basis of this design. Containers with 15-inch-diameter bores would require (scaled-up) outside diameters of 100 inches and 190 inches, respectively. Rings of those diameters are considered too large to be practicably manufactured and assembled.

Theoretically, a ring-fluid-ring container can be designed to a maximum pressure capability of $p_{max} \approx 1,000,000$ psi. It would have a multiring inner unit. However, the external-size requirements make such a design impracticable as was the case for the ring-fluid-segment container.

Conclusions and Recommendations

Bore pressures of 450,000 psi corresponding to 10^6 cycles life are found to be theoretically possible in hydrostatic-extrusion containers using the fluid-supported multiring concept. Container designs with 6-inch-diameter bores appear to be practicable to construct. However, outside-diameter requirements of 15-inch-diameter-bore containers appear too large to be practicable at this time.

Theoretical analyses have been based on postulated fatigue behavior of highstrength steels. Experiments to obtain actual fatigue data of high-strength steel cylinders under cyclic pressures up to 450,000 psi is needed before the predictions of theory can be verified. A potential problem in such an experimental fatigue program is foreseen: the fatigue specimens will have to be heavy-walled containers in order to support the high pressures. Therefore, an alternative experimental research program consisting of two steps is recommended:

- A preliminary analysis aimed at designing small specimens pressurized and mechanically loaded to simulate the stress condition at the bore of a container, and
- (2) Construction and testing of simulated specimens.

XXXI

DESIGN REQUIREMENTS AND LIMITATIONS FOR HIGH-PRESSURE CONTAINERS

As already indicated, the <u>theoretically</u> predicted maximum-pressure capability for the five containers considered in detail in the present study are as follows for 10^4 to 10^5 cycles life:

Container	Maximum Pressure, p, psi
Multiring	300 000
Ring-segment	300,000
Ring-fluid-segment $(p_3/p = 0.3)$	~1,000,000
Pin-segment	210,000
Ring-fluid-ring (multiring inner unit)	~1,000,000

These predictions, based on the fatigue strengths of steels with an ultimate tensile strength of 300,000 psi for the liner and 200,000 psi for the outer cylinders or components, apply to any operating temperature provided these are the strengths at that temperature.

For liners with ultimate tensile strengths much greater than 300,000 psi, the theoretical maximum pressure capability of the various designs may be improved appreciably. This is true if it can be assumed that the higher strength materials would exhibit the same fatigue behavior as that shown in Figure 42 for steels with ultimate tensile strength ranging from 250,000-310,000 psi at room temperature. (Tensile strengths of 410,000 psi have been reported for AISI M50 steel. If the previous assumption is correct, then a multiring or ring-segment container with an M50 liner would have a theoretical maximum pressure capability of 410,000 psi. However, these containers may require that some ductile outer cylinders have ultimate tensile strengths greater than 200,000 psi.)

Possible Manufacturing and Assembling Limitations

It is important to note that the <u>theoretical</u> pressures given in the above tabulation may not be achievable for each design because of <u>practicable</u> design limitations. For example, the outside diameters required for designs having 6- and 15-inch bore diameters and maximum pressures up to 450,000 psi are as follows:

the make in the second	Maximum Pressure, p,	Outside Diameter, inches			
Container	psi	6-inch-Bore Design	15-inch-Bore Design		
Multiring	300,000	51.0	127.5		
Ring-segment	300,000	60.0	150.0		
Ring-fluid-segment	450,000	88.0	218.0		
Pin-segment	210,000	90.4	180.2		
Ring-fluid-ring (Example 2)	450,000	76.0	190.0		

It may be impossible to obtain steel cylinders in such large sizes (10- to 50-foot diameters) with ultimate strengths of 200,000 psi, and it may be impossible to machine and transport such large cylinders. Also heat treatment of heavy sections may be a problem. This may not be the case for pin-segment container, however. In this instance, it may be possible to forge the large steel pins (18.2 inches and 45.4 inches in diameter respectively, based on a design shear stress of 50,000 psi in fatigue for the pins) and the segments (thick plates). This indicates an advantage of the pin-segment design for vessels with $p \leq 210,000$ psi.

A pin-segment arrangement may also be used to advantage as a replacement for the outer cylinder in the other container designs. This would help overcome the difficulties associated with the large steel cylinders. A wire wrap or strip wrap could also be used to this advantage as a replacement to outer cylinders.

The limitations in some of the designs due to large-diameter outer cylinders may also be partially overcome by using the autofrettage process to provide some additional prestress at the liner bore. The process introduces compressive prestresses by plastic deformation of the bore. This approach could reduce the size and number of outer rings that otherwise would be needed to achieve the total prestress by shrink fitting alone. In fact, the autofrettage process could be used to improve the size efficiency of all the design concepts considered. However, if autofrettaging is employed, then high-strength steels with appreciable amounts of ductility should be selected for the liner because the process requires plastic deformation of the bore.

In addition to the potential problem of cylinder size, the <u>theoretical</u> pressures may not be possible to achieve because excessive interferences may be required for shrink-fit assembly. The maximum interferences required for the designs are as follows:

Container	Maximum Pressure, p, psi	Maximum Interference Required, inch/inch			
Multiring	300,000	$\Delta_1 / r_1 = 0.0036$			
Ring-segment ($k_2 = 1.1, \frac{E_2}{E_1} = 3.0$)	300,000	$\Delta_{12}/r_1 = 0.0028$			
${1}$ Ring-fluid-segment (k ₂ = 2.0)	450,000	$\Delta_{12}/r_1 = 0.0129$			
Pin-segment	210,000	None, except for a small amount to take up slack during assembly			
Ring-fluid-ring (Example 2)	450,000	$\Delta_1 / r_1 = 0.0080$			

For the multiring container, the interference required between the liner and Cylinder 2 as manufactured is $\Delta_1/r_1 = 0.0036$ in./in. This is a reasonable value and it corresponds to a temperature difference of 400 to 500 F for assembly. However, the interference as manufactured is not always the same as the interference as assembled. Suppose that the multiring container is assembled ring by ring from the inside out. Each ring expands as it is shrunk on and the assembly interference progressively increases beyond the manufactured interference. Formulas for the assembly interference can also be derived. Derivations are given in Appendix II.

The interference required for the ring-fluid-segment container is $\Delta_{12}/r_1 = 0.0129$ in./in. This interference requirement is severe, if not impossible, especially when one considers assembling not only the liner and Cylinder 3, but also a number of segments all at the same time. (Δ_{12} is the interference required between the liner, segments, and Cylinder 3. Δ_{12} is also the assembly interference as well as the manufactured interference since the liner, Cylinder 3, and the segments must be assembled simultaneously.) The large magnitude for Δ_{12} is primarily due to large radial elastic deformation of the segments under pressure. This is shown as follows: from Equation (19a) it is found that

$$\frac{E_2 (u_1 - u_2)}{r_1 p_1} = 0.69 \text{ for } k_2 = 2 \text{ and } p_2 = p_1/k_2$$

where u_1 and u_2 are the radial displacements of the segment and r_1 and r_2 , respectively. From a computer calculation for the ring-fluid-segment container, p_1 at pressure $(\sigma_r = -p_1 \text{ at } r_1)$, is found to be $p_1/\sigma_1 = 2.2$. Thus,

$$\frac{E_2 (u_1 - u_2)}{r_1 \sigma_1} = 2.2 (0.69) = 1.518$$

For p/ $\sigma_1 = 2.87$ and p = 450,000 psi, $\sigma_1 = 157,000$ psi. Hence, $\frac{u_1 - u_2}{r_1} = 0.00795$ in./in.

for $\sigma_1 = 157,000$ psi and $E_2 = 30 \times 10^6$ psi, and it is evident that large interference, $\Delta_{12} = 0.0129$ in./in., is required to overcome large deformation of the segments under pressure. This is a disadvantage for the containers having segments in their designs.

Another potential disadvantage of these designs is the possible problem of gouging the liner with the corners of the segments if the components are assembled by pressing. A further factor that must be considered in the design of segments is bending deformation. This is discussed in Appendix I.

The severe interference requirements imposed by the segments are reduced if the segment size (k_2) is reduced and if a higher modulus material is used for the segments. These effects are shown above for the ring-segment container that has a lower interference requirement; i.e., $\Delta_{12} = 0.0028$ in./in. However, selection of a high modulus material must be done with care because tensile stresses do develop in the segments as shown in Appendix I and many high-modulus materials have low tensile strengths.

Thus, it is seen that some <u>theoretical</u> container designs for high pressure may be impossible to fabricate because of the large outside diameters and interferences required. In order to obtain a more realistic evaluation of the various design concepts, predictions of pressure capability are made for more <u>practicable</u> design requirements, i.e., outside diameters limited to 72 inches and the interferences limited to 0.007 in./ in. maximum. These predictions are as follows for 10^4-10^5 cycles life:

Con	tainer	Bore Diameter, inches	Outside Diameter, inches	Number of Components, N	Maximum Pressure, p, psi
Multiring	$\begin{cases} (k_1 = 2.0) \\ (k_1 = 1.5) \end{cases}$	6 15	51.0 72.0	5 7	300,000 275,000
Ring-segment ($k_2 = 1.1, E_2/E_1 = 3.0$)	$\begin{cases} (k_1 = 2.0) \\ (k_1 = 1.5) \end{cases}$	6 15	60.0 72.0	6 8	290,000 265,000
Ring=fluid-segment ($k_1 = 1.5$, $k_2 = 2.0$)	$ \left\{ \begin{array}{l} (p_3/p=0.3,\ k_3=1.25)\\ (p_3/p=0.3,\ k_3=1.20) \end{array} \right. $	6 15	72.0 72.0	10 4	286,000 160,000
Pin-segment $(k_1 = 1.3, k_2 = 2.0)$		6 15	72.0 (a)	3	195,000
Ring-fluid-ring ^(b)	$\begin{cases} (k_1 = 2.0) \\ (k_1 = 1.60) \end{cases}$	6 15	60.0 72.0	8 4	450,000 219,000

(a) OD ≤ 72.0 not possible for 10^4 - 10^5 cycles life and $\alpha_r = \alpha_m = 0.35$ if no prestress is provided. (b) One ring inner unit. $p_1/p = (k_1^2 + 1)/(2k_1^2)$.

It is evident that lower maximum pressures are now predicted, particularly for the 15inch-bore designs. The reduction in pressure capability is due only to the restriction in outside diameter for the multiring, ring-segment, and pin-segment containers. However, both the outside diameter and interference limitations reduce the predicted pressure for the ring-fluid segment container. The reduction for this container is severe and is caused by three effects. The first is excessive deformation of the segments for $k_2 = 2.0$. The other effects are coupled; reducing the outside diameter while maintaining the design pressure increases the interference required, but limiting the interference causes a reduction in maximum pressure because the interference depends upon the pressure.

Residual Stress Limitations

A container designed for a specific cyclic pressure requires certain residual stresses (prestresses) at operating temperature. It is also important, however, to check the residual stresses at room temperature because of differences in thermal expansion.

Calculations of residual stresses are given here for the multiring container as an example. (Residual stresses and operating stresses can be determined for all containers using the computer programs listed in Appendix III.) The specific container design discussed here is the one considered in the foregoing section for a bore diameter of 6 inches. Calculations are performed for design applications at room temperature, 500 F, and 1000 F. The material data assumed are given in Table XLVI. The liner material is assumed to be 18 percent Ni maraging steel, and the outer cylinders are assumed to be made of modified H-11 steel. The differences in thermal expansion for these materials are likely to be the largest expected among the steels that may be used.

and the second se		and a set of the set o
70 F	500 F	1000 F
Modulus of Elast	icity, psi	
26.5 x 106 30.0 x 106	23.0 x 106 27.4 x 106	18.7 x 106 22.8 x 106
cient of Thermal Ex	xpansion, in./in./F	
5.6 x 10-6 7.12 x 10-6	5.6 x 10-6 7.25 x 10-6	5.6 x 10-6 7.37 x 10-6
	70 F <u>Modulus of Elast</u> 26.5 x 106 30.0 x 106 cient of Thermal Ex 5.6 x 10-6 7.12 x 10-6	70 F500 FModulus of Elasticity, psi 26.5×10^{6} 23.0×10^{6} 30.0×10^{6} 27.4×10^{6} cient of Thermal Expansion, in. /in. /F 5.6×10^{-6} 5.6×10^{-6} 7.12×10^{-6} 7.25×10^{-6}

TABLE XLVI. ELEVATED-TEMPERATURE DATA FOR 18 PERCENT NICKEL MARAGING STEEL AND H-11 STEEL^(a)

(a) Poisson's ratio taken as constant, $\nu = 0.3$ for both materials.

Results are given in Table XLVII. The range and mean stress parameters were $\alpha_r = 0.5$ and $\alpha_m = -0.5$, respectively. The results show that the excessive residual stresses at room temperature occur for the multi-ring container having a required prestress, $\sigma_{\theta} = -\sigma_1$ at 500 F and 1000 F; i.e., the residual stress $\sigma_{\theta} < -\sigma_1$ at room temperature, where σ_1 is the design stress and $\sigma_1 \leq$ ultimate tensile strength. The reason for this is the larger interferences required for elevated-temperature application as shown in Table XLVII. Larger interferences are necessary for high-temperature applications because the outer rings expand more than the liner due to the differences in thermal expansions as shown in Table XLVI. On the other hand, reduction of the temperature from operating temperature to room temperature causes the outer rings to tend to contract more than the liner. The liner resists the contraction and the residual interface pressures are increased, thereby increasing the magnitude of the residual hoop stress at the bore.

If the multiring container is to be used at 500 F and 1000 F with the material properties given in Table XLVI, then the prestress requirement, $\sigma_{\theta} = -\sigma_1$ at temperature $(\alpha_m = -0.5)$ has to be relaxed. Accordingly, calculations of residual stresses and interferences were rerun for $\alpha_m = -0.3$ (prestress $\sigma_{\theta} = -0.8 \sigma_1$ at temperature). The results are shown in Table XLVIII. With $\alpha_m = -0.3$, excessive residual stresses at room temperature are avoided for the 500 F design. However, for operation at 1000 F, $\alpha_m > -0.3$ is necessary since $\sigma_{\theta} < -\sigma_1$ at room temperature for the 1000 F design with $\alpha_m = -0.3$.

Decreasing the interference fit (from those in Table XLVII to those in Table XLVIII), in order to avoid excessive residual stresses at room temperature, increase $(\sigma_{\theta})_{\max}$ from 0 to positive values. As pointed out in the latter part of the Fatigue Criteria section, zero to small $(\sigma_{\theta})_{\max}$ is expected to be beneficial in preventing the detrimental effect of fluid pressure from entering voids in the material. Therefore, if excessive residual stresses are to be avoided in containers designed for high temperatures, and if $(\sigma_{\theta})_{\max}$ is to be kept small, then the thermal coefficients of expansion of the component parts of the container should be more closely matched than those of Table XLVI. Preferably the coefficient of thermal expansion should be larger for the liner than for the outer cylinders; this would cause a reduction rather than an increase in residual stresses upon decreasing the temperature from operating temperature to room temperature.

· · · · · · · · · · · · · · · · · · ·	Stresses at Bore of Liner(b)								
	Residual Stresses at RT			Prestresses at Temperature			Operating Stress at Pressure and Temperature		
	σ_r/σ_1	$\sigma_{\theta}/\sigma_{1}$	s/σl	σ_r/σ_1	σθ/σι	s/o ₁	σ_r/σ_1	$\sigma_{\theta} / \sigma_{1}$	s/σ_1
RT Design	0	-1.000	-0.5000	0	-1.0000	-0.5000	-0.9727	0	0.4863
500 F Design	0	-1.1230	-0.5615	0	-1.0000	-0.5000	-0.9727	0	0.4863
1000 F Design	0	-1.2998	-0.6499	0	-1.0000	-0.5000	-0.9727	0	0.4863
		Dimensionless Interference Required as Manufactured (C							
		Between Cylind		lers Between					
			1 and 2	(b).	outer Cylinders n and n + 1				
		for	p = 300,000	psi ^(d) ,					
		EA1/r1p			$E \Delta_n / r_n p$				
RT Design		0.358			0.343				
500 F Design		0.454			0.343				
1000 F Design		0.533			0.343				

TABLE XLVII. LINER-BORE STRESSES AND INTERFERENCES FOR A 6-INCH-BORE MULTIRING CONTAINER WITH K = 8.5, N = 5, $k_1 = 2.0$, $k_n = 1.44$, n = 2, $\alpha_r = 0.5$, AND $\alpha_m = -0.5(a)$

(a) The k_n, K, a_r, and a_m are defined in the list of symbols. Material data are given in Table XLVI. The liner is 18% Ni steel and the outer cylinders are H-11 steel.1

(b) σ_r is the radial stress, σ_{θ} the hoop stress, S the shear stress (S = $(\sigma_{\theta} - \sigma_r)/2$), and σ_1 is the design strength - less than or equal to the ultimate tensile strength of the liner.

(c) E is the modulus of elasticity of the outer cylinders. Δ_n is interference in inches between cylinders n and n + 1. r_n is the outer radius of cylinder n.

(d) $E\Delta_1/r_1p$, at elevated temperatures, depends on p. $\sigma_1 = 310,000$ psi is required, (p = 0.9727 σ_1).

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The second states and the	Stresses at Bore of Liner ^(b)									
	Residual Stresses at RT			Prestresses at Temperature			Operating Stress at Pressure and Temperature			
	σ_r/σ_1	<i>σθ</i> /σ1	s/o1	σ_r/σ_1	σθ/σι	s/σ_1	σ_r/σ_1	$\sigma_{\theta}/\sigma_{1}$	s/σ_1	
PT Design	0	0 8000	0 4000	0	0 8000	0 1000	0 0727	0 2000	0 5962	
500 F Design	0	-0.8000	-0.4000	0	-0.8000	-0.4000	-0.9727	0.2000	0.5005	
1000 F Design	0	-0.9054	-0. 4327	0	-0.8000	-0.4000	-0.9727	0.2000	0.5803	
			0.0200		0.0000	0. 1000	0. / ! = !	0.2000	0.0000	
		Dimensionless Interference Required as Manufactured(c)								
		Between Cylind l and 2 for p = 300,000 p		ders Between Outer Cylinders psi ^(d) , n and n + 1						
						Cylinders nd n + 1				
			$E\Delta_1/r_1p$		ΕΔ	EAn/rp				
		the second second	1 1-	and the second	- d' theme	<u> </u>				
RT Design			0.217		0	. 304				
500 F Design			0.309		0.304					
1000 F Design			0.383		0	. 304				

TABLE XLVIII. LINER-BORE STRESSES AND INTERFERENCES FOR A 6-INCH-BORE MULTIRING CONTAINER WITH K = 8.5, N = 5, $k_1 = 2.0$, $k_n = 1.44$, $n \stackrel{>}{=} 2$, $\alpha_r = 0.5$, AND $\alpha_m = -0.3^{(a)}$

(a) The k_n, K, a_r, and a_m are defined in the list of symbols. Material data are given in Table XLVI. The liner is 18% Ni steel and the outer cylinders are H-11 steel.

(b) σ_r is the radial stress, σ_{θ} the hoop stress, S the shear stress (S = $(\sigma_{\theta} - \sigma_r)/2$), and σ_1 is the design strength - less than or equal to the ultimate tensile strength of the liner.

(c) E is the modulus of elasticity of the outer cylinder. Δ_n is interference in inches between cylinders n and n + 1. r_n is the outer radius of cylinder n.

(d) $E\Delta_1/r_{1p}$, at elevated temperatures, depends on p. $\sigma_1 = 310,000$ psi is required (p = 0.9727 σ_1).

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Other Possible Material Limitations

It has been postulated that a maximum-tensile-stress fatigue criterion applies to the high-strength liner. Accordingly, fatigue data from uniaxial tension and rotatingbeam bending tests were used to evaluate fatigue behavior of liners for high-pressure containers. However, the state of stress in an open-end hydrostatic extrusion container is biaxial and in a closed-end container a triaxial state of stress exists. (A triaxial state of stress may also occur in a shrink-fit open-end container where axial stresses may be produced by interface friction between shrink-fitted rings.) The effect of combined stresses on the fatigue strength of high-strength steels is unknown. It is pointed out, however, that the analyses performed in this study allow for arbitrary material behavior; i. e., the fatigue parameters, α_r and α_m , used in the analyses are left arbitrary in the equations and could be determined from combined-stress fatigue experiments.

It has also been postulated that a compressive mean stress may benefit material fatigue strength under cyclic fluid pressure. However, biaxial and triaxial fatigue behavior under compressive mean stress is unknown. Even fatigue data in the uniaxial case are lacking for conditions of compressive mean stress.

Also unknown is the possible fracture of high-strength steels under large compressive stresses. Pugh and Green⁽⁴³⁾ and Crossland and Dearden⁽⁴⁴⁾ found for cast iron that the fracture strain and ductility (and the maximum shear stress at fracture) are increased by superimposing hydrostatic pressure. Bridgman⁽⁴⁵⁾ found similiar but less conclusive results for steel. These are favorable results for the effect of true hydrostatic pressure, but the possibility of similiar behavior when only one principal stress (the radial stress in a container) is highly compressive is unknown and should be investigated. This is a particularly important factor because the difference between the hoop stress and the high compressive radial stress represents an extremely large shear stress.

The effect of a brittle-ductile transition in high-strength steels on the fatigue behavior near and above the transition temperature is another factor which may need to be considered.